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The ATLAS Beam Condition and Beam Loss Monitors

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Motivation

- LHC equipment failure: resulting beam losses potentially dangerous to the ATLAS Inner Detector (ID)
- Experience show that beam accidents can happen

Tevatron Beam accident: caused by Roman Pot reinserting itself in the beam after it had been issued the retract commands



- Total energy stored in one LHC beam (2808 bunches with 10¹¹ protons at 7TeV → 350MJ) more than 100-times higher than in previous accelerators like Tevatron or HERA
- Time constants of magnets: shortest \sim few LHC turns (order of ms) \rightarrow if beam losses detected early enough, the beam can be dumped in time to prevent beam accident (beam is dumped within 3 turns $\sim 270\mu$ s)

ATALS BCM and BLM goal

Protection

- Passive:
 - ATLAS and CMS have **TAS collimators**: protects Inner Detector from direct beam incidences
 - TAS (Target Absorber Secondaries) collimators: at $z=\pm 18m$ which protect the Inner Triplet of quadrupoles from secondaries produced in p-p collisions
- Active:

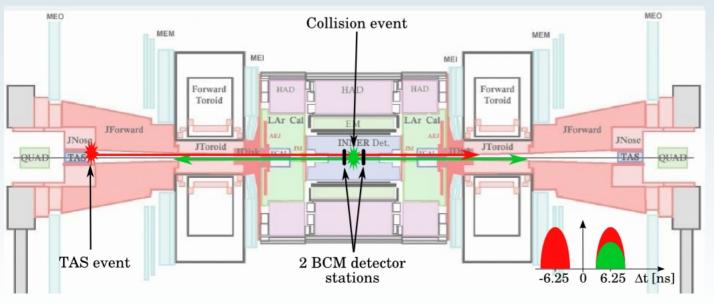
Machine Beam Loss Monitors, Beam Positions Monitors... can fire beam abort

- ATLAS Beam Condition Monitor (BCM) and Beam Loss Monitor (BLM)
 - Designed for fast detection of early signs of beam instabilities (due to incorrect magnet settings, magnet trips, failures...)
 - Issue a beam abort in case of beam failures
 - BCM
 - Particle counter
 - Will additionally provide a coarse relative **luminosity** measurement (complementary information to LUCID-ATLAS main luminosity monitor)
 - BLM
 - Induced current measurement

ATLAS BCM: principle of operation

Time of flight measurement to distinguish between collisions and background events (beam gas, halo, TAS scraping)

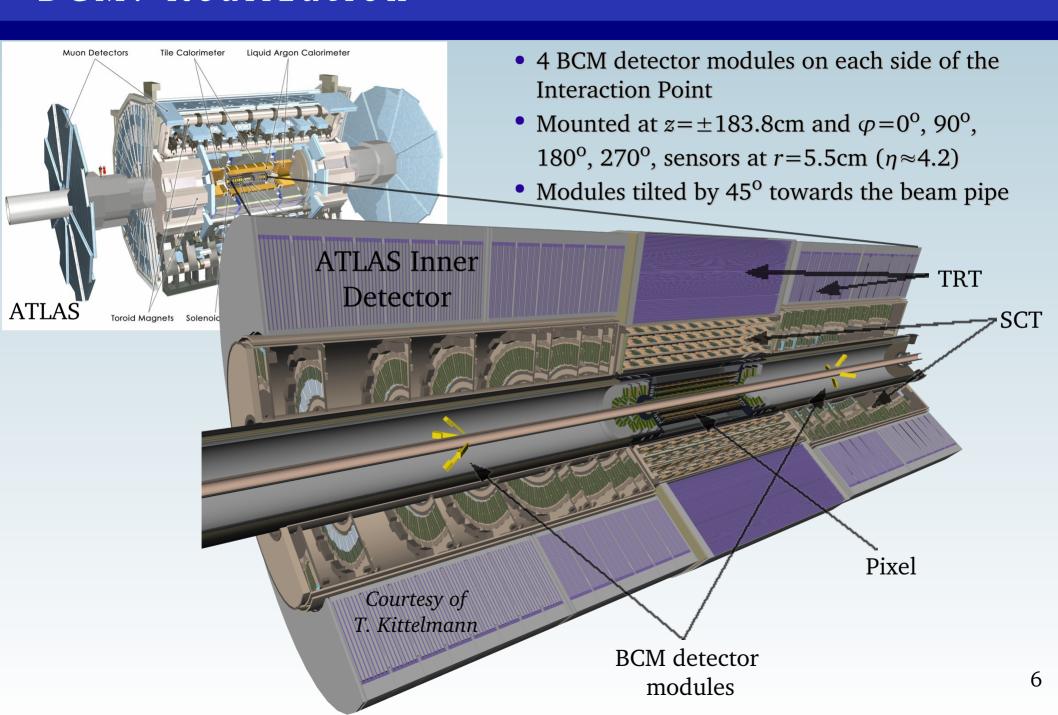
- measurement every proton bunch crossing (BC 25 ns)
- place 2 detector stations at $z=\pm 1.9$ m:
 - particles from **collisions** reach both stations at the same time (6.25ns after collisions themselves) every BC
 - particles from **background** interactions
 - reach the nearest station 12.5ns (½ BC) before particles from collisions (6.25ns before collisions themselves)
 - reach the furthest station at the same time as particles from collisions
 - > use **"out of time"** hits to identify the background events
 - > use "in time" hits to monitor luminosity



Requirements:

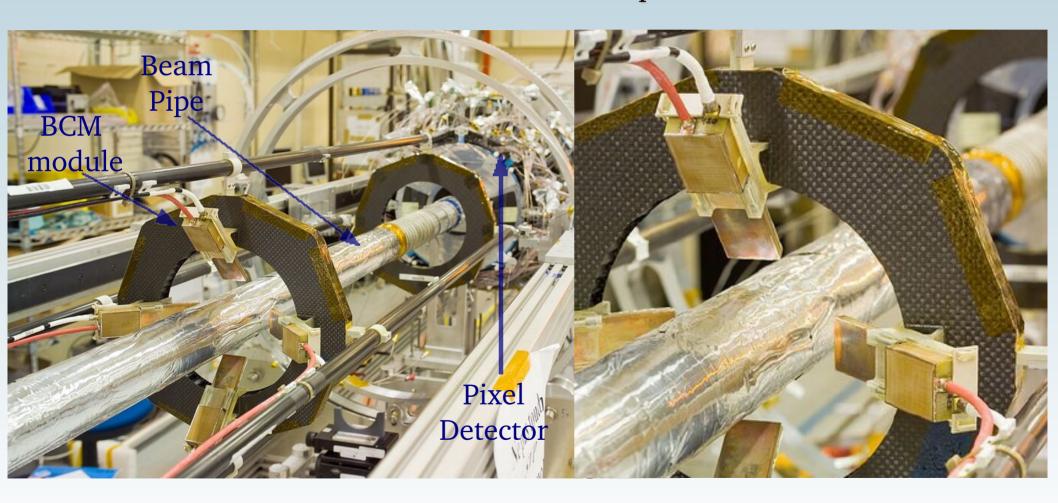
- fast and radiation hard detector & electronics:
 - >rise time ~1ns
 - >pulse width ~3ns
 - >baseline restoration ∼10ns
 - >ionization dose ~0.5 MGy, 10^{15} particles/cm² in 10 years
- MIP sensitivity

BCM: Realization



BCM: Detector Modules Installed

BCM modules were installed on Beam Pipe Support Structure (BPSS) in November 2006 and lowered into ATLAS pit in June 2007



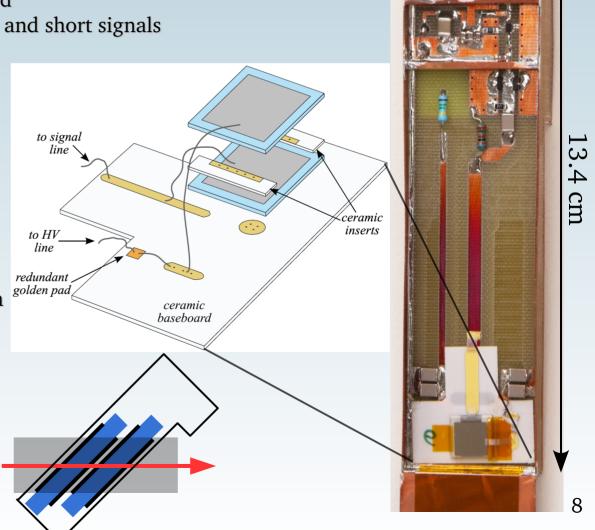
BCM Detector modules

Poly-crystalline CVD diamond sensors

- developed by RD42 and Element Six Ltd.
- radiation hard: shown to withstand 10¹⁵p/cm²
- low leakage current → no cooling required
- operated at high drift field $2V/\mu m \rightarrow$ fast and short signals

Double – decker assembly

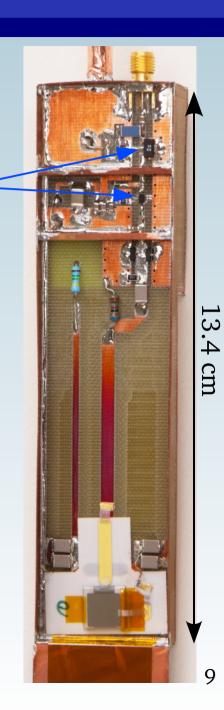
- 2 back-to-back sensors each with
 - Thickness 500µm,
 - CCD @1V/cm ~220μm
 - Size: 10×10 mm²
 - Contact size: 8×8 mm²
 - Operated at 2V/μm (1000V)
- Double signal compared to assembly with one sensor, but noise not measured to be two times higher
- For 45° particle incidence signal increase by factor $\sqrt{2} \rightarrow$ modules installed at 45° to the beam pipe



BCM Detector modules

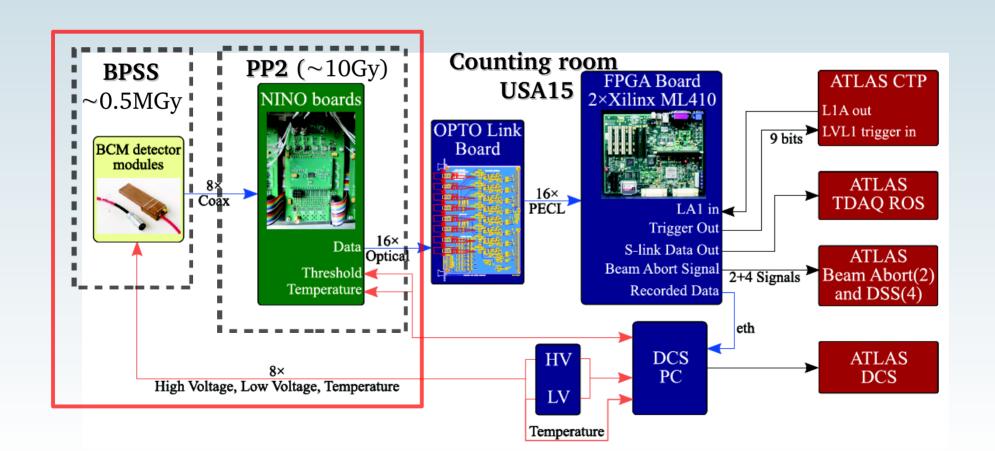
Front end electronics

- 2 stage amplifier:
 - 1st stage: Agilent MGA-62653, 500MHz (22db)
 - 2st stage: Mini Circuit GALI-52, 1GHz (20dB)
- Measurements showed (confirmed with simulation):
 - Limiting BWL to 200MHz improved S/N by 1.3
 - rise time worse by 70% and FWHM by 60%, but still fit to requirements
 - → 4th order 200MHz filter integrated on digitisation board before digitisation (NINO chip)



BCM: Readout chain

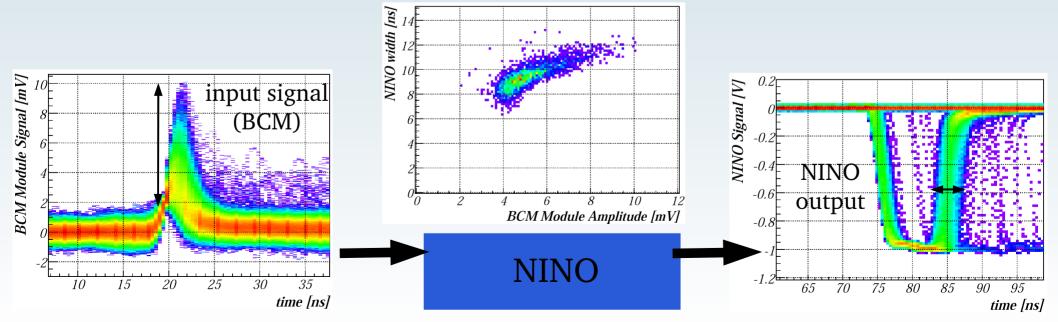
- Analogue signals from BCM detector modules routed behind calorimeter (lower radiation levels) where they are "digitised" by custom made board based on NINO chip
- Each module connected to separate NINO electronics board



BCM: "Digitisation" electronics board

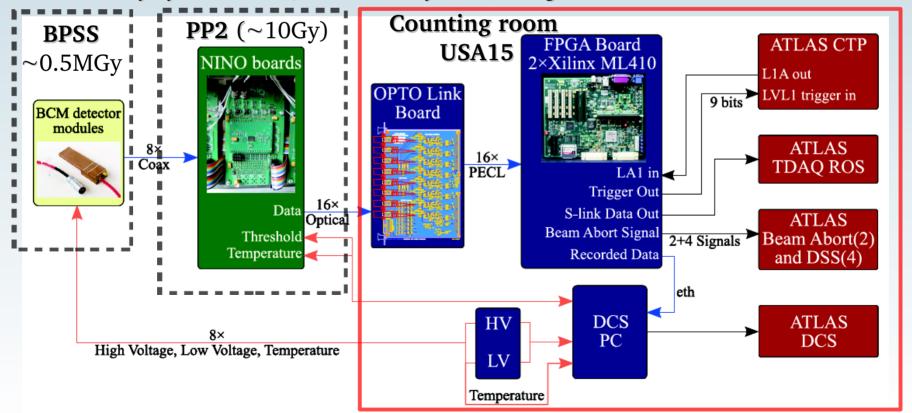
NINO chip

- Developed for ALICE ToF (F. Anghinolfi et al.)
- Radiation tolerant, fabricated in 0.25µm IBM process
- Rise time < 1ns, jitter <25ps, Min. detection threshold 10fC
- Time-over-threshold amplifier-discriminator (adjustable threshold) chip
- Width of LVDS output signal depends on input charge
- Before input to NINO chip: signal charge split in two channels in ratio of 1:11 to increase the dynamic range → high and low gain channels
- Low gain channels need ~10 times more MIPs traversing the sensor simultaneously than high gain channels to show the signal



BCM: Readout chain

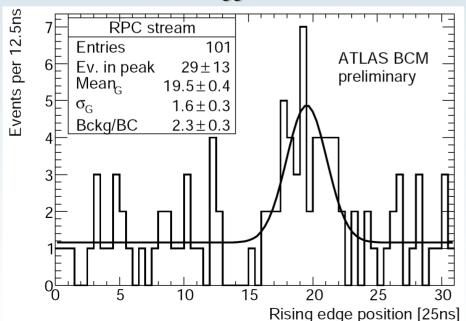
- Optical signals transmitted through 70m of optical fibres to USA15 counting room
- Optical signals transformed to PECL (2 optical receiver boards) and connected to 2 data processing units based on Xilinx Vitrex-4 FPGA
- Processing units connected to
 - ATLAS Central Trigger Processor (CTP): BCM provides 9 bits
 - ATLAS Data acquisition (TDAQ): on trigger signal (LVL1A) from CTP, BCM data from 31 bunch crossings is formatted and sent of ATLAS DAQ readout chain
 - ATLAS Detector Control System (DCS): monitoring rates,...
 - Detector Safety Systems (DSS), Beam abort system (through CIBU-Control Interlocks Beam User)

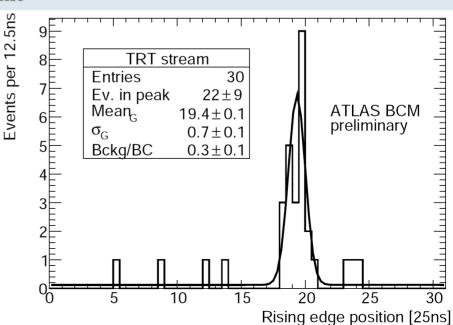


ATLAS BCM: Cosmic data

November 2008: combined ATLAS Inner Detector cosmic data taking

- Two different triggers:
 - Resistive Plate Chambers (RPC) of Muon system
 - Fast-OR mechanism of Transition Radiation Tracker (TRT)
- On each trigger from CTP: BCM sends data (signal rising edge and width) from 31 BCs to ATLAS DAQ chain
- Timing distribution of RPC and TRT triggered BCM hits:
 - Superimposed is a fit to Gaussian signal and a random background.
 - Gaussian peak wider with RPC trigger: better jitter of TRT trigger
 - Probability for noise hit in BC: $\sim 10^{-7}$
 - RPC: about 10M triggers needed for 9 true BCM hit
 - TRT: about 1M triggers needed for 9 true BCM hit

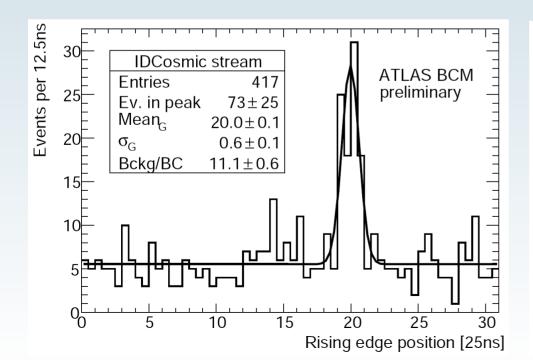


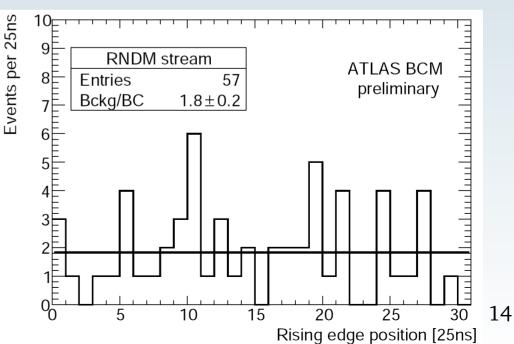


ATLAS BCM: Cosmic data

June 2009: ATLAS cosmic data taking

- IDCosmic trigger stream: selects events with at least 1 track reconstructed in Inner Detector at trigger LVL2
- RNDM trigger stream: random trigger
- Timing plots:
 - RNDM stream: flat as expected
 - IDCosmic stream: Gaussian width ~ as for TRT stream in November cosmic run
- Probability for noise hit per 1 BC: 8-7 times higher then in November 2008 run, due to higher thresholds in 2008
- Signal: 1M IDCosmic triggers give 6 true BCM hits



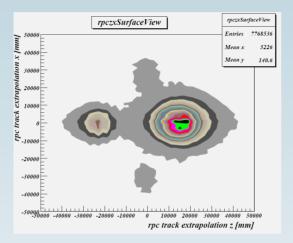


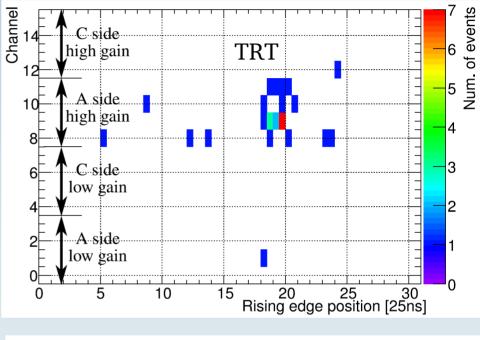
ATLAS BCM: Cosmic data

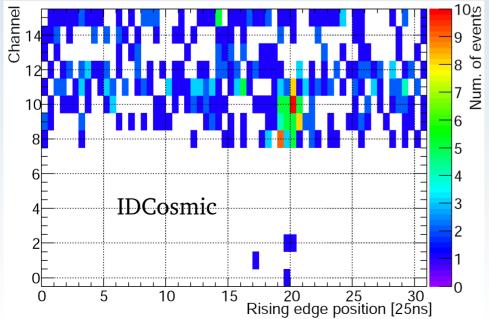
Timing distribution of BCM hits over channels:

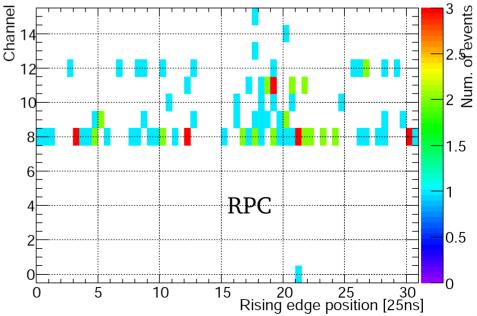
 Almost no hits on C side (attributed to unequal size of 2 main ATLAS shafts)

From: M. Bianco,"ATLAS RPC commissioning status and cosmic ray test results", PIC2008









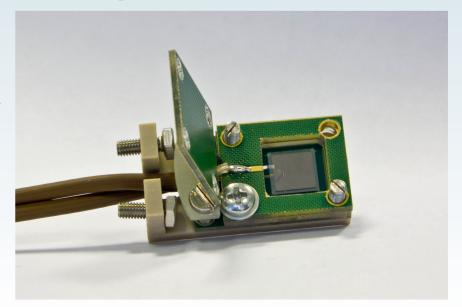
ATLAS BLM

ATLAS Beam Loss Monitor – ATLAS BLM

- Independent system
- Recently added as a backup for ATLAS BCM
- Goal: only protection → much simpler than BCM
- Provide complementary information to BCM, but can be used as standalone in case of problems with BCM
- Readout electronics based on the LHC BLM system
 - Major change: ATLAS BLM uses diamond sensors instead of ionisation chambers (LHC BLM)
 - Other: different LV powering scheme, firmware changes in the readout cards,...

• Sensors:

- one pCVD 8×8mm² diamond, 500µm thick. metallization 7×7mm²
- operated at +500V
- current @500V typically <1-2pA



ATLAS BLM: Detector modules

view towards IP SIDE A **12 detector modules** installed in May 2008 • 6 on each side of IP, installed on Inner **Detector End Plate** • Close to IP: $z=\pm 3450$ mm, r=65mm SCT Inner Detector End Plate Pixel TRT **ATLAS** Inner Detector BCMmodules Courtesy of BLM

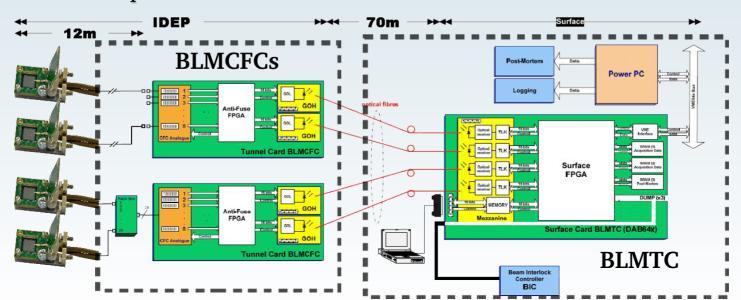
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T. Kittelmann

modules

ATLAS BLM: Readout

- Measurement of radiation **induced current** in sensors, integrated over predefined time constants ranging from 40μ s to 84s.
- **Digitization** of induced current: converted to frequency by radiation tolerant BLMCFC ("CFC card", behind calorimeter)
- Digitised information transmitted through optical fibers to USA15 counting room, **recorded** by BLMTC ("threshold card") based on Altera FPGA:
 - BLMTC inserted in VME crate
 - Through Single Board Computer, VME bus used recording the post mortem buffer and for monitoring readings (sent to ATLAS Detector Control System)
 - Connected to LCH **beam abort:** beam abort issued if readings from 2 modules on one side exceed a predefine threshold



Summary

- ATLAS BCM will monitor beam conditions close to IP using TOF measurement
 - Goal:
 - Protection
 - Additionally, relative luminosity measurement
 - pCVD diamonds as sensor material
 - 2 diamonds in a back-to-back configuration at 45° towards the beam
 - First experience with the system obtained in the last year and a half



• ATLAS BLM:

- **Redundant** system for safety purposes
- Induced current measurement
- pCVD diamond sensors
- Looking forward to using them in the real LHC environment

Backup slides

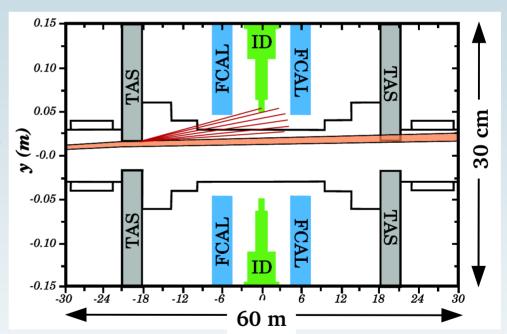
Beam Loss Scenarios

Single-turn losses

- Likely to occur during injection or beam dump processes
- ATLAS can be rated the 'safest' of all LHC interaction points (far away from injection, dump)
- Pilot bunch (single bunch of low intensity, 5×10^9 p@450GeV; 360J) will be used to check the magnet settings

Simulation of beam orbits with wrong magnet settings (D. Bocian) exhibit scenarios with pilot beam scrapping the beam pipe or TAS collimator (most likely scenario), no direct hitting of Inner Detector (ID)

TAS (Target Absorber Secondaries) collimators: at $z=\pm 18m$ which protect the Inner Triplet of quadrupoles from secondaries produced in p-p collisions



Multi-turn losses

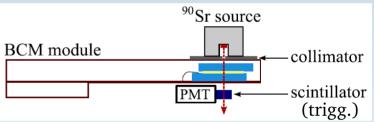
- Beam degradation due to equipment failure, magnet trips, wrong magnet settings...
- Time constants of magnets: shortest ~ few LHC turns (order of ms) → can abort the beam if detected early (beam is dumped within 3 turns ~ 270μs)

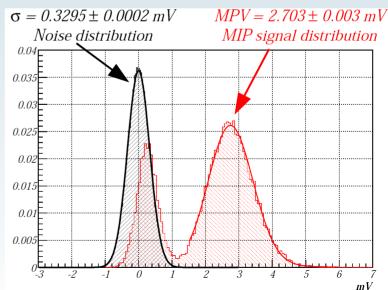
QA of BCM Modules

Qualification tests with final modules to select 8 for installation

- Raw sensor characterization:
 - I/V, CCD
- Module performance
 - All modules subjected to thermo-mechanical test
 - infant mortality test (12h @80°)
 - accelerated ageing for one of the module (14h @120° 10 years at 20°)
 - thermal cycling (10 cycles from -25° to 45°)
 - Module performance checked before and after these tests with ⁹⁰Sr setup
 - no change in S/N observed
 - for normal particle incidence: typical S/N≈7–7.5

MODULE	404	405	408	410	413	420	422	424
Polarity	+	+	-	+	+	-	-	_
MPV [mV]	2.4	2.3	2.3	2.7	2.2	2.7	2.4	2.7
S/N	6.6	6.9	7.0	7.8	7.0	7.9	7.4	8.2
Current [nA]	70	35	20	25	250	200	40	10



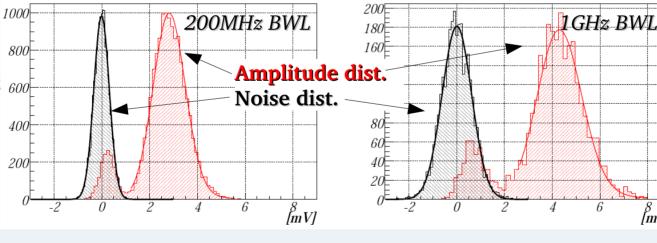


BCM Detector modules

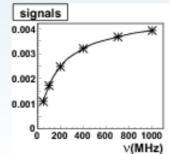
Front end electronics

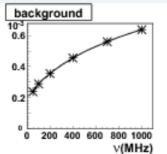
- 2 stage amplifier:
 - 1st stage: Agilent MGA-62653, 500MHz (22db)
 - 2st stage: Mini Circuit GALI-52, 1GHz (20dB) -
- Limiting BWL to 200MHz improved S/N by 1.3 (and rise time worse by 70% and FWHM by 60%, but still fit to requirements)
 - → 4th order 200MHz filter integrated before digitization (on NINO board)

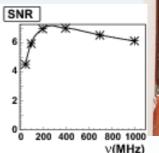
Lab. Tests with 600 MIPs at 90° 400 incidence



Off-line analysis of waveforms recorded at full BWL: optimum S/N with 1st order filter with cut-off frequency 200-400 MHz





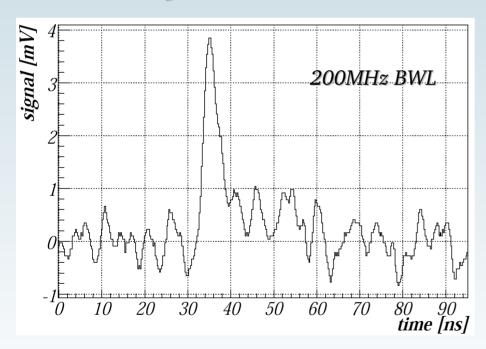


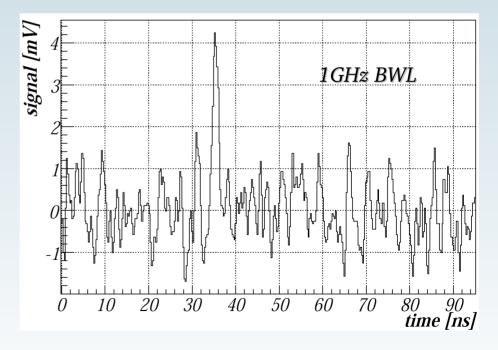


BCM: Analogue signals

Signals recorded with 200MHz BWL at the readout

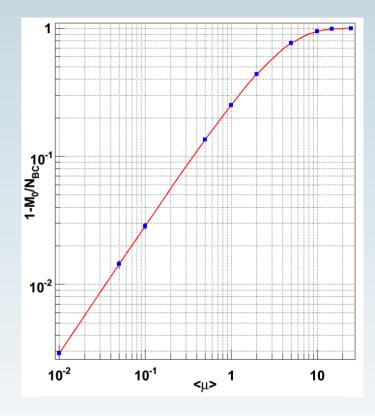
- Typical S/N with MIP at 90° incidence in the lab. tests: 7-7.5
- Most probable amplitude produced by MIP at 90° in the lab tests: 2.2 2.7 mV
- Mean rise time 1.4ns
- Mean FWHM 2.9ns
- Timing resolution better than 400ps (thresholds: 0.1-2 MP amplitude)





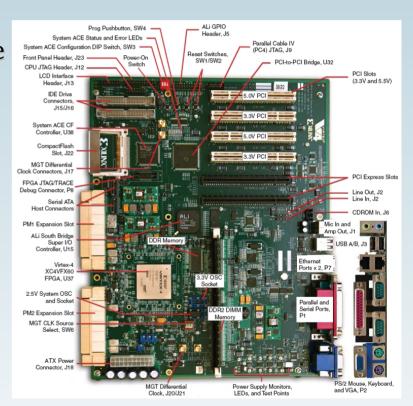
BCM: luminosity

- BCM will contribute to luminosity monitoring with
 - Monitor instantaneous luminosity
 - Vertex position monitoring
 - Determine dead time
 - Beam separation scans
- First algorithms will be based on non-empty event counting
 - Monitoring of luminosity per BCID
 - Providing instantaneous luminosity at Hz rate
- Monte-Carlo simulations under-way to provide initial calibration used before first beam-separation scans, and understanding systematic



BCM: Processing units & signal analysis

- Input signal sampled with 2.56 GHz:
 64 samples of 390ps width for each proton bunch crossing (BC-25ns)
- Raw data stored in DDR2 circular buffer (for >more than 3×10^6 BCs \rightarrow 1000 last LHC turns)
- For each BC:
 - Signal rising edge and width of at most first 2 signals are reconstructed and stored in DDR cyclic buffer (more than 2×10⁶1BCs → 800 LHC turns)
 - On trigger signal (LVL1A) from CTP: BCM data from 31 Bunch crossings is formatted and sent of ATLAS DAQ readout chain
 - "In-time" and "out-of-time" coincidences, high multiplicity for low and high gain channels
 - 9 trigger bits to CTP
 - Beam abort (if beam conditions have reached unacceptable level)
 - Alarm and warning signals in less sent to DSS, DCS



BCM: beam abort

Beam abort algorithms:

- For initial phase: 4 Low threshold channels (horizontal modules) + 3 high threshold channels (vertical modules)
- Monitor and use later:
 - X/Y (3+4 condition reached in consecutive X out of Y BCs)
 - Leaky bucket (X/Y with forgetting factor)

BLM: induced current

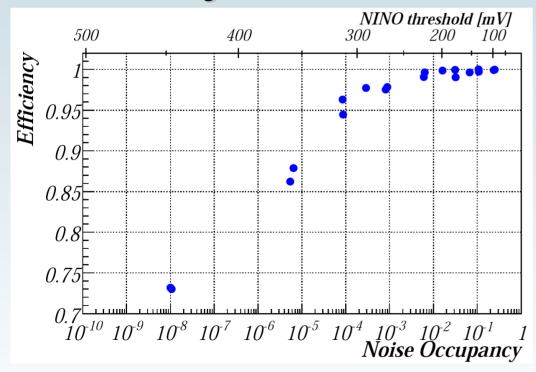
Currents in BLM modules:

- Current from 14TeV *p-p* collisions:
 - \sim 15nA/module (at design luminosity, 10^{34} /cm⁻¹s⁻¹)
 - Estimated form the Total Ionisation Dose plots
 - Scales with luminosity
- Accidents (simulation)
 - 7 TeV p on TAS gives \sim 1 MIP/BLM module
 - 1 MIP in diamond generates ∼1 fC of charge
 - 25pA of current "spike" for single occurrence (1 bunch, possible for pilot bunch)
 - 40nA of continuous loss every BC (much more likely for full LHC bunch structure)
- Diamond dark currents in magnetic field O(10pA)
- Initially threshold for 40µs reading: set to 50nA

BCM: performance up to FPGA input

Estimated performance of BCM system in ATLAS (up to FPGA input) for high gain channels:

- Median S/N (for MIPs at 45° incidence) ≈ 9
- Noise RMS $\sigma \approx 64$ mV
- Median signal ≈ 570mV



- 1MIP efficiency versus noise occupancy (noise rate scaled to 25ns interval – bunch crossing in ATLAS)
 - efficiency 0.95 0.99 for occupancies $10^{-3} 10^{-4}$
- The exact level of fake rate depends on what kind of logical combination of signals will be used in ATLAS

BCM: performance

Noise rate measured in ATLAS pit:

 \bullet extracted noise RMS σ 51-68mV (different det. modules and NINO boards) agrees with estimation (64mV)

