

# ATLAS Diamond Beam Conditions Monitor

*Irena Dolenc*

*on behalf of the ATLAS BCM Collaboration*

*Presented in Irena's absence by Harris Kagan*

# ATLAS BCM collaboration members



## JSI Ljubljana

V. Cindro  
I. Dolenc  
A. Gorišek  
G. Kramberger  
B. Maček  
I. Mandić  
E. Margan  
M. Mikuž  
M. Zavrtanik



## OSU, Columbus

H. Kagan,  
S. Smith



## Univ. of Applied Science, Wiener Neustadt

E. Griessmayer  
H. Frais-Kölbl  
M. Niegl



## CERN

D. Dobos,  
H. Pernegger,  
P. Weilhammer



## Univ. of Toronto

C. Cadabeschi  
D. Tardif  
W. Trischuk

ATLAS BCM web page: <https://twiki.cern.ch/twiki/bin/view/Atlas/BcmWiki>

# Motivation

The goal of BCM system inside the ATLAS Inner Detector:

- ▣ Monitor beam conditions and distinguish each bunch crossing between **normal collisions** and **background events** during normal running
  - ▣ measure background rate (beam halo, beam gas) close to the vertex
  - ▣ measure collision rate and provide (bunch by bunch) relative luminosity information (additional measurement to LUCID, ATLAS main luminosity monitor)
- ▣ Primary goal: **protection** in case of larger beam losses
  - ▣ fast detection of early signs of beam instabilities (due to incorrect magnet settings, trips, ...)
  - ▣ Issue warning and alarm signals for equipment protection
  - ▣ Input to ATLAS Detector Safety System and LHC Beam Abort



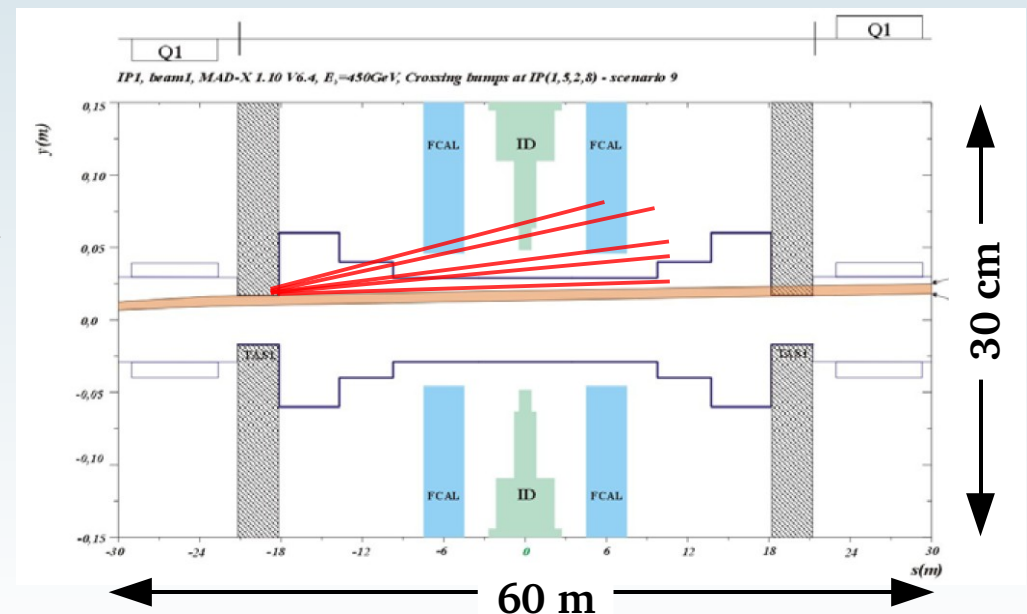
# Beam Loss Scenarios

## Multi-turn losses

- beam degradation (equipment failure, wrong magnet settings...)
- time constants of magnets  $\sim \text{ms}$   $\rightarrow$  can abort the beam if detected early

## Single-turn losses of 360MJ/beam

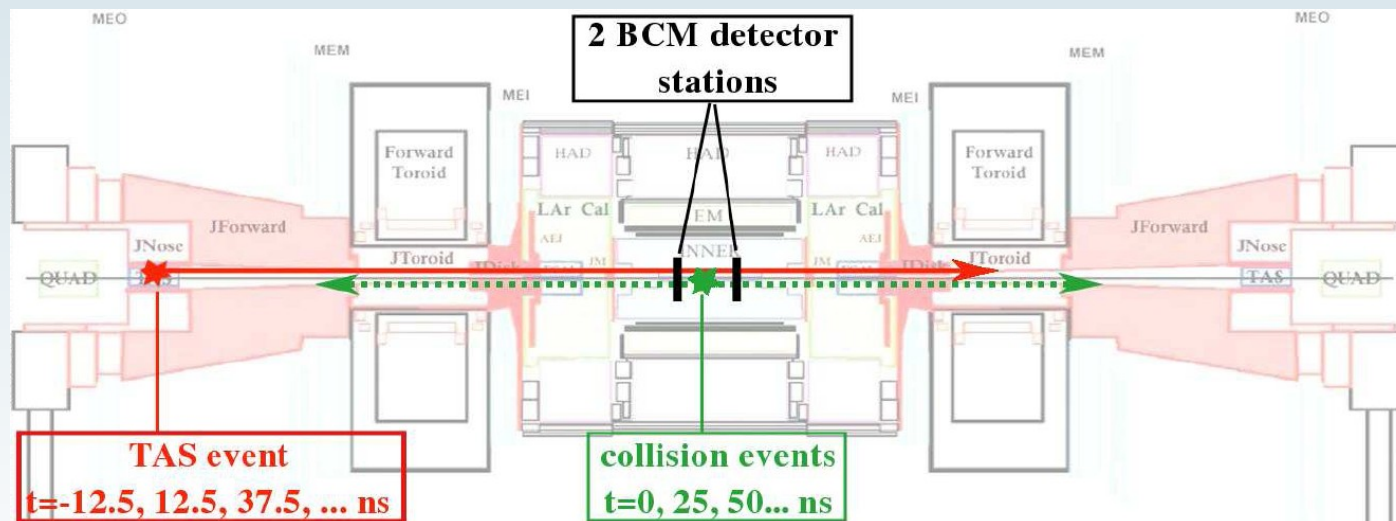
- likely to occur during injection or beam dump processes
- IR1 (ATLAS) can be rated the 'safest' of all interaction points (far away from injection, dump)
- pilot bunch (single bunch of low intensity,  $5 \times 10^9 \text{ p@450 GeV}$ ; 360J) will be used to check the magnet settings
- simulations of beam orbits with wrong magnet settings (D. Bocian) exhibit scenarios with beam scrapping TAS Cu collimator



# ATLAS BCM principle of operation

**Time of flight** measurement to distinguish between collisions and downstream background events (beam gas, halo, TAS scraping... )

- ▢ measurement every proton bunch crossing (25 ns)
- ▢ place 2 detector stations at  $z = \pm 1.9\text{m}$ :
  - ▢ secondary particles from **collisions** reach both stations at the same time (6 ns after collisions)
  - ▢ secondary particles from upstream **background** interactions reach nearest station 12.5ns before secondary particles from collisions (6 ns before collisions)
- use “**out of time**” hits to identify the background events
- use “**in time**” hits to monitor luminosity

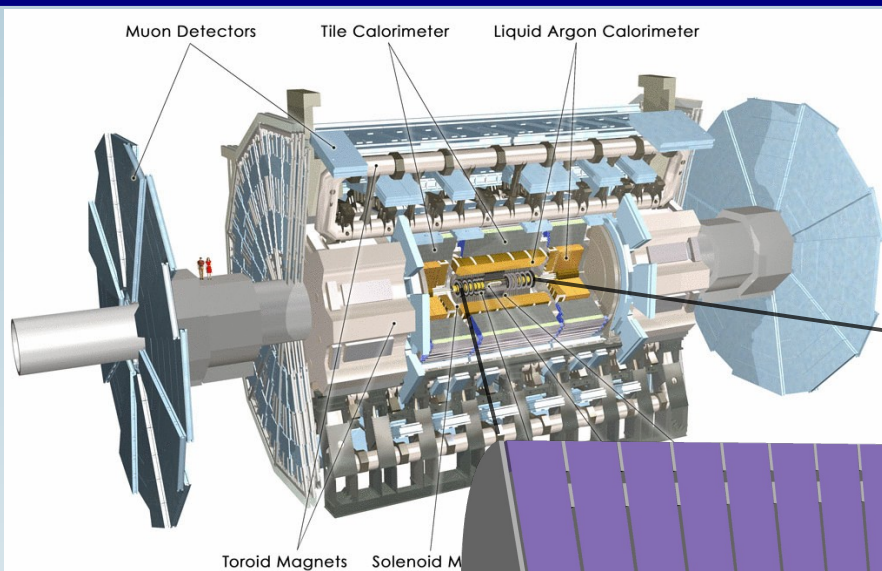


## Requirements:

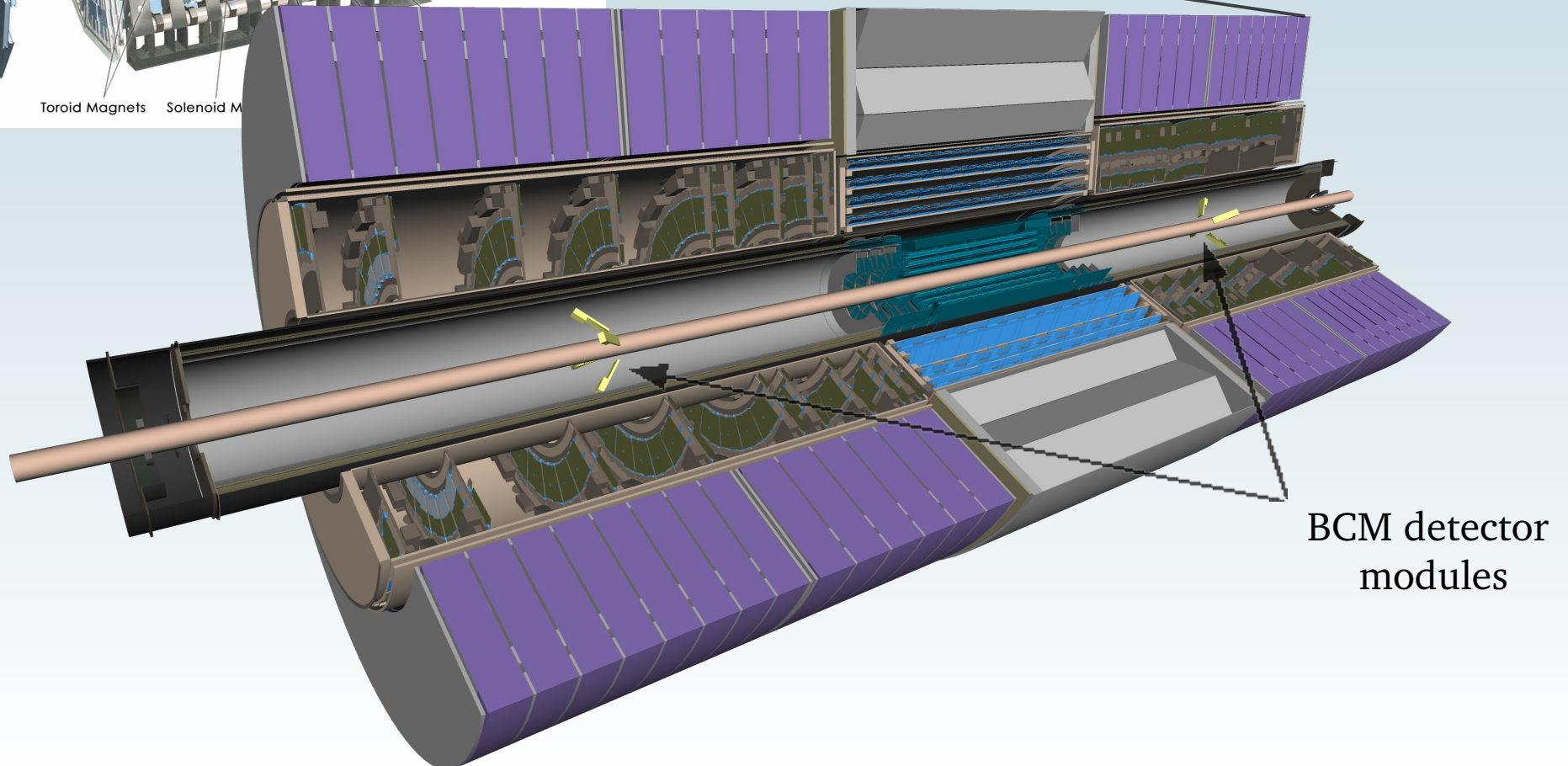
- ▢ fast and radiation hard detector & electronics:
  - rise time  $\sim 1\text{ns}$
  - pulse width  $\sim 3\text{ns}$
  - baseline restoration  $\sim 10\text{ns}$
  - ionization dose  $\sim 0.5 \text{ MGy}$ ,  $10^{15} \text{ particles/cm}^2$  in 10 years
- ▢ MIP sensitivity



# Realization



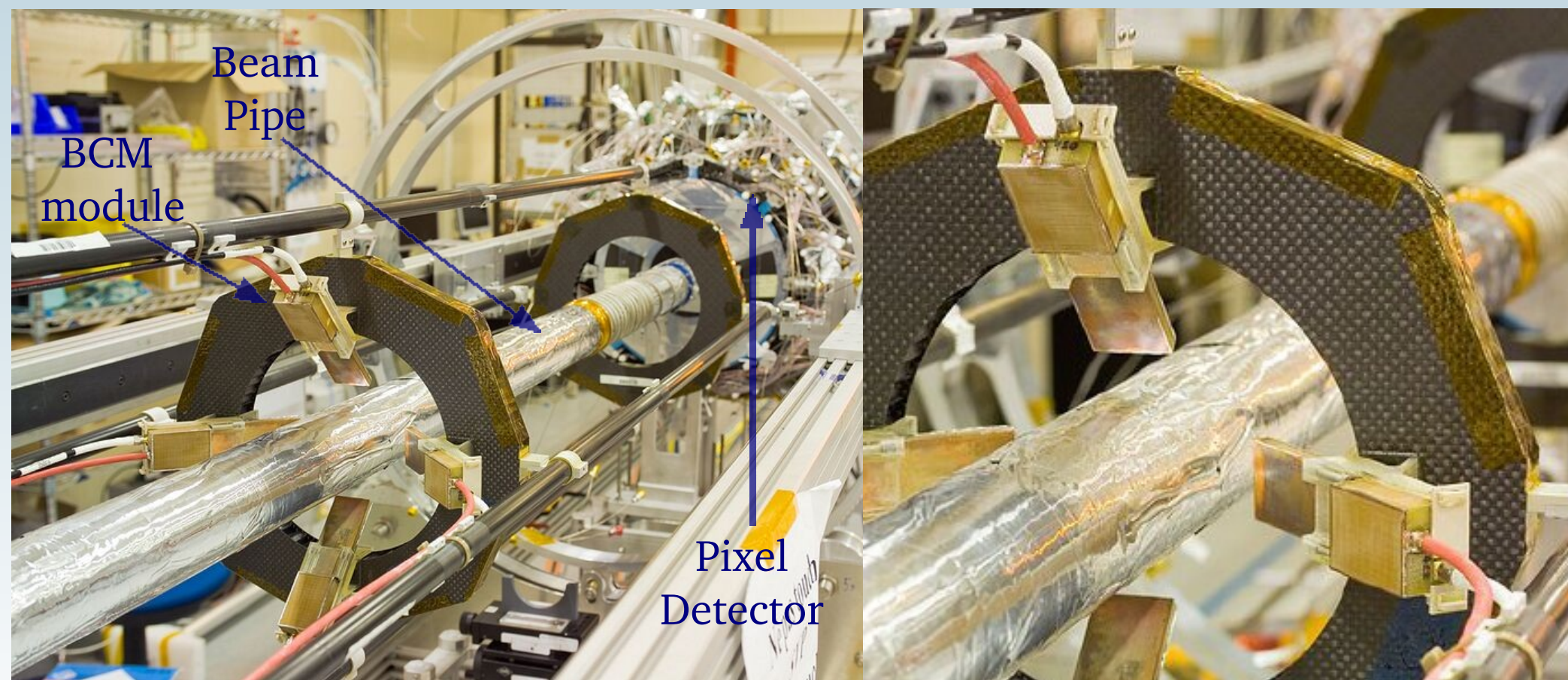
- 4 BCM detector modules on each side of the Pixel detector
- Mounted on Beam Pipe Support Structure at  $z = \pm 183.8\text{cm}$ , sensors at  $r = 5.5\text{cm}$  ( $\eta \approx 4.2$ )



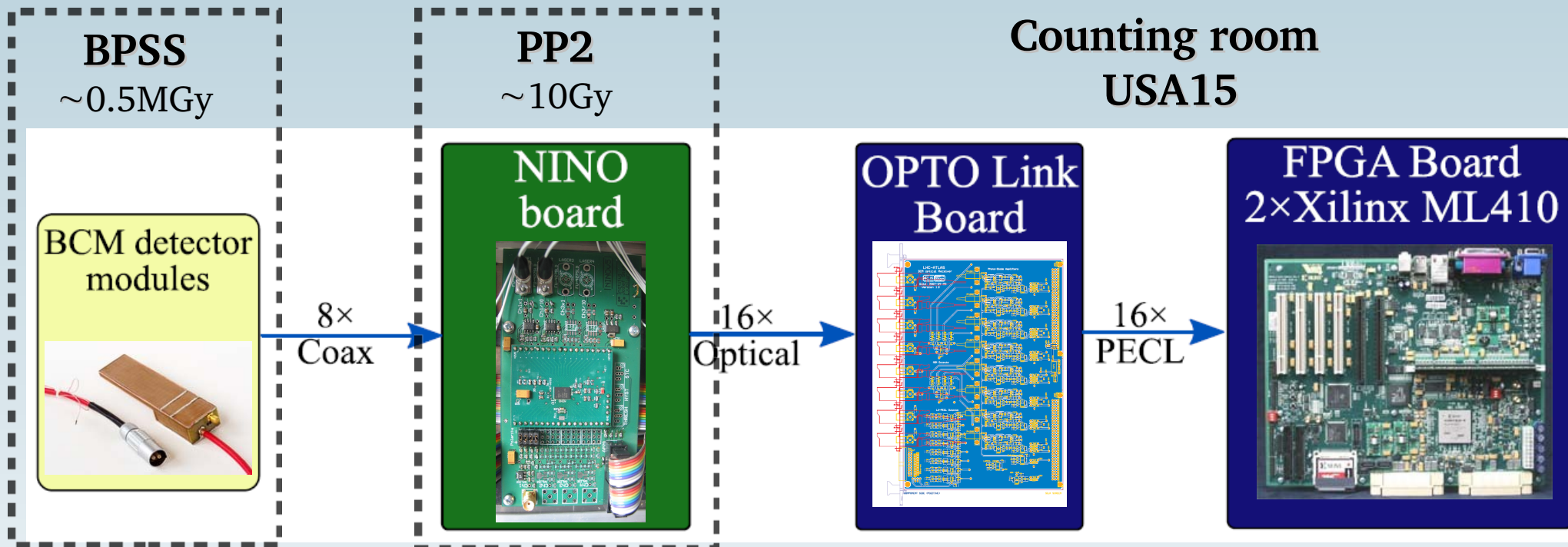


# BCM Detector Modules Installed

BCM modules were installed on Beam Pipe Support Structure in November 2006 and lowered into ATLAS pit in June 2007



# BCM System - Schematics





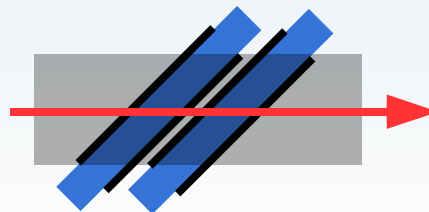
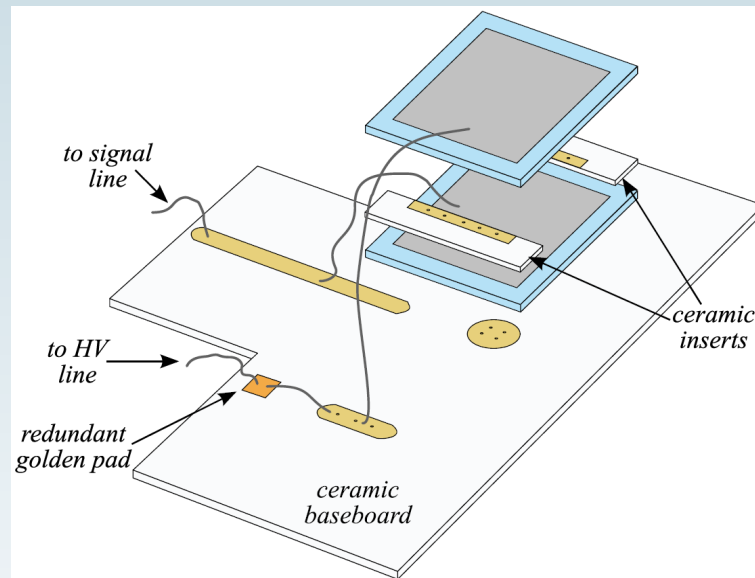
# BCM Detector modules

## Poly-crystalline CVD diamond sensors

- ▣ developed by RD42 and Element Six Ltd.
- ▣ radiation hard: shown to withstand  $10^{15} \text{ p/cm}^2$
- ▣ low leakage current → no cooling required
- ▣ fast & short signals – operate at high drift field  $2 \text{ V/}\mu\text{m}$

## Double – decker assembly

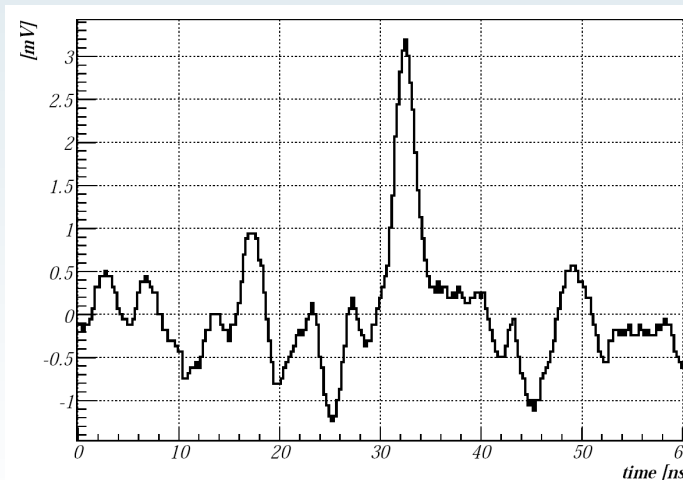
- ▣ 2 back-to-back sensors each with
  - ▣ thickness  $500 \mu\text{m}$ ,
  - ▣ CCD @  $1 \text{ V/cm} \sim 220 \mu\text{m}$
  - ▣ Size:  $10 \times 10 \text{ mm}^2$
  - ▣ Contact size:  $8 \times 8 \text{ mm}^2$
  - ▣ Operated at  $2 \text{ V/}\mu\text{m}$  (1000V)
- ▣ Double signal compared to assembly with one sensor, but noise not measured to be two times higher
- ▣ For  $45^\circ$  particle incidence signal increase by factor  $\sqrt{2}$  → modules installed at  $45^\circ$  to the beam pipe



# BCM Detector modules

## Front end electronics

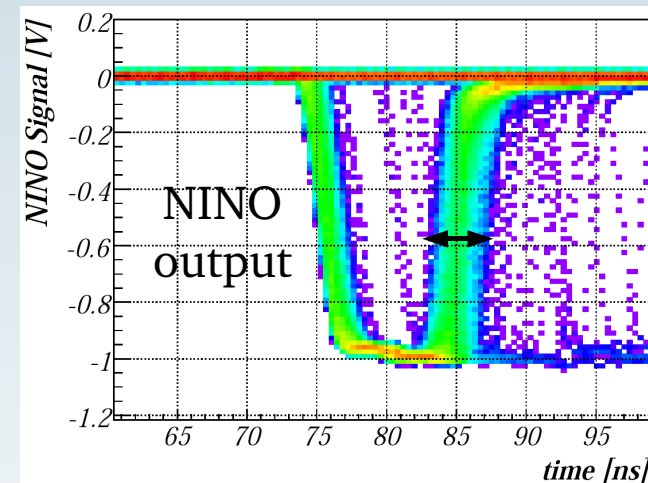
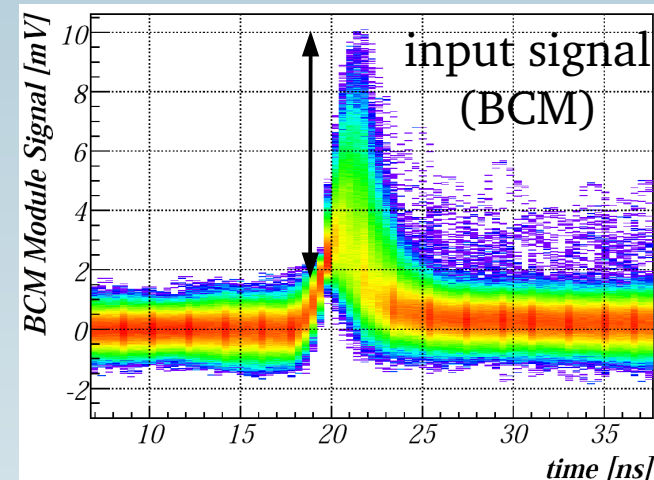
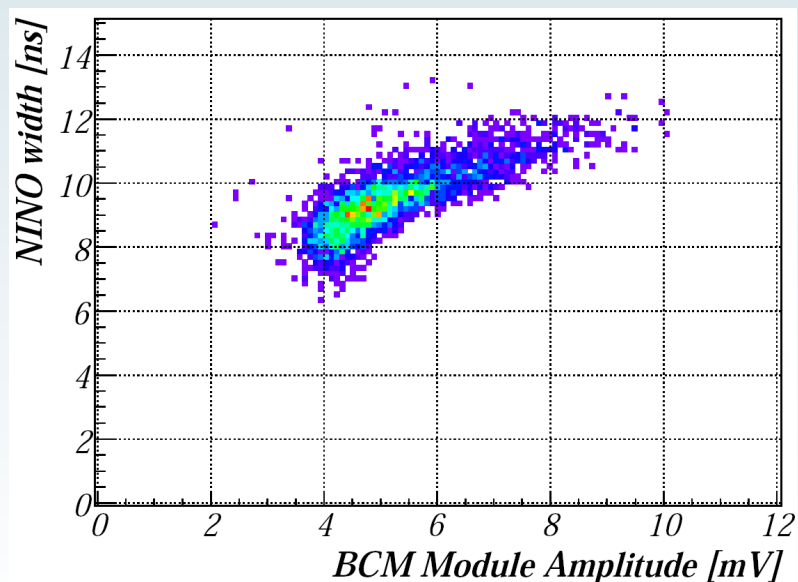
- ▣ 2 stage amplifier:
  - ▣ 1<sup>st</sup> stage: Agilent MGA-62653, 1GHz (20dB)
  - ▣ 2<sup>nd</sup> stage: Mini Circuit GALI-52 500MHz (22dB)
- ▣ Limiting BWL to 200MHz improved S/N by 50% (but 10% worse timing resolution)  
→ 4<sup>th</sup> order 200MHz filter integrated on NINO board before digitization
- ▣ Signals recorded with LeCroy LC564A digital oscilloscope with 200MHz BWL:
  - ▣ mean rise time 1.4ns
  - ▣ mean FWHM 2.9ns



# NINO board

## NINO chip

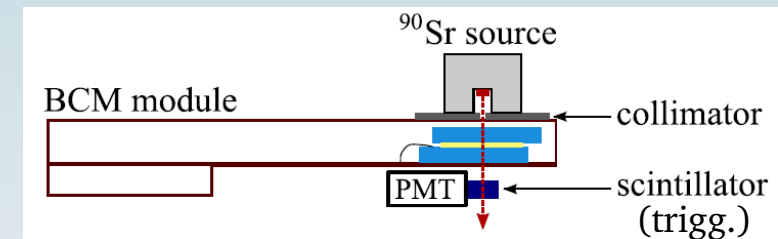
- ▣ Developed for ALICE ToF (F. Anghinolfi et al.)
- ▣ Radiation tolerant
- ▣ Fabricated in 0.25 $\mu$ m IBM process
- ▣ Peaking time < 1ns, jitter < 25ps
- ▣ Min. detection threshold 10fC
- ▣ Time-over-threshold amplifier-discriminator chip
- ▣ width of LVDS output signal depends on input charge



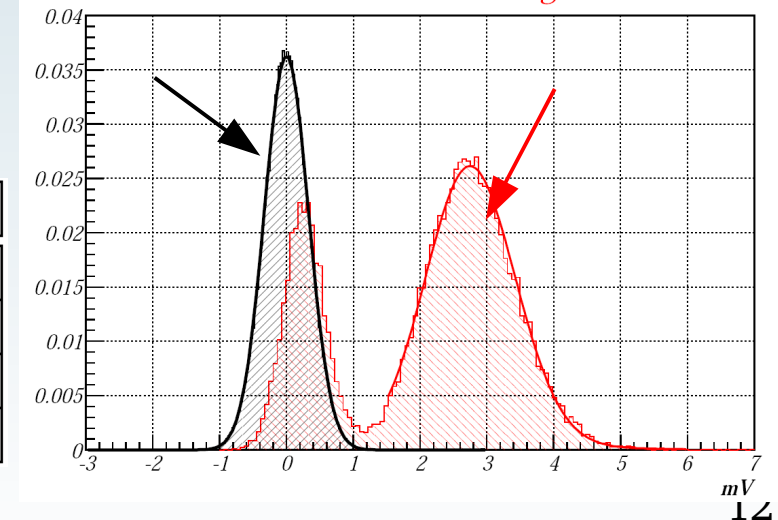
# QA of BCM Modules

Qualification tests with final modules to select 8 for installation

- ▣ **Raw sensor characterization:**
  - ▣ I/V, CCD
- ▣ **Module performance**
  - ▣ All modules subjected to **thermo-mechanical test**
    - ▣ infant mortality test (12h @80°)
    - ▣ accelerated ageing for one of the module (14h @120° 10 years at 20°)
  - ▣ thermal cycling (10 cycles from -25° to 45°)
  - ▣ **Module performance checked** before and after these tests with  $^{90}\text{Sr}$  setup
    - ▣ no change in S/N observed
    - ▣ for normal particle incidence: typical  $S/N \approx 7-7.5$



$\sigma = 0.3295 \pm 0.0002 \text{ mV}$        $MPV = 2.703 \pm 0.003 \text{ mV}$   
*Noise distribution*      *MIP signal distribution*



MODULE	404	405	408	410	413	420	422	424
Polarity	+	+	-	+	+	-	-	-
MPV [mV]	2.4	2.3	2.3	2.7	2.2	2.7	2.4	2.7
S/N	6.6	6.9	7.0	7.8	7.0	7.9	7.4	8.2
Current [nA]	70	35	20	25	250	200	40	10



# Test Beam at CERN SPS/PS in 2006: Setup

Bonn Telescope:  
4 Si-strip tracking modules  
(4 XY points along pion path)

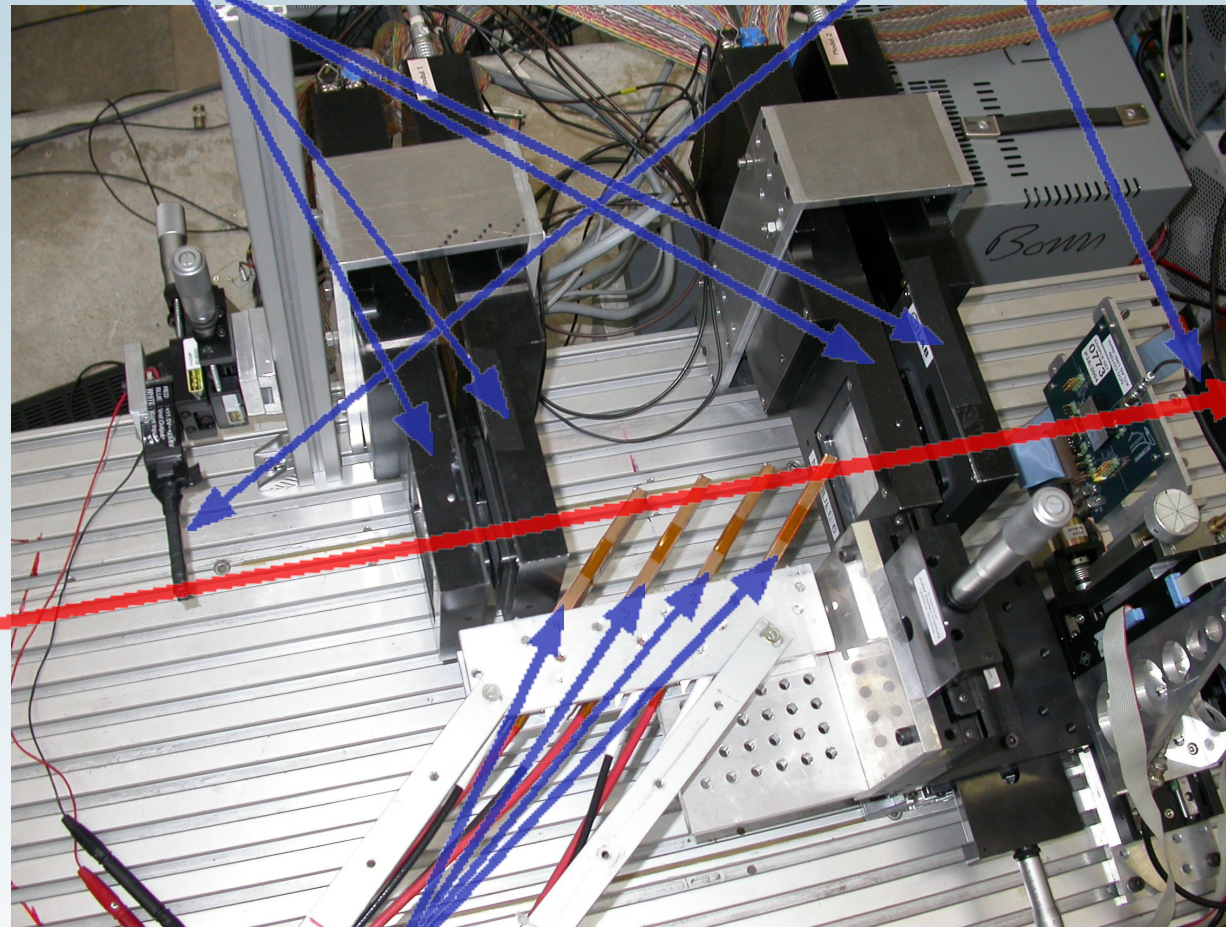
Trigger scintillators

**Pion Beam**

T9:  $p=3.5$  GeV/c

T11:  $p=12$  GeV/c

H8:  $p=20, 100$  GeV/c



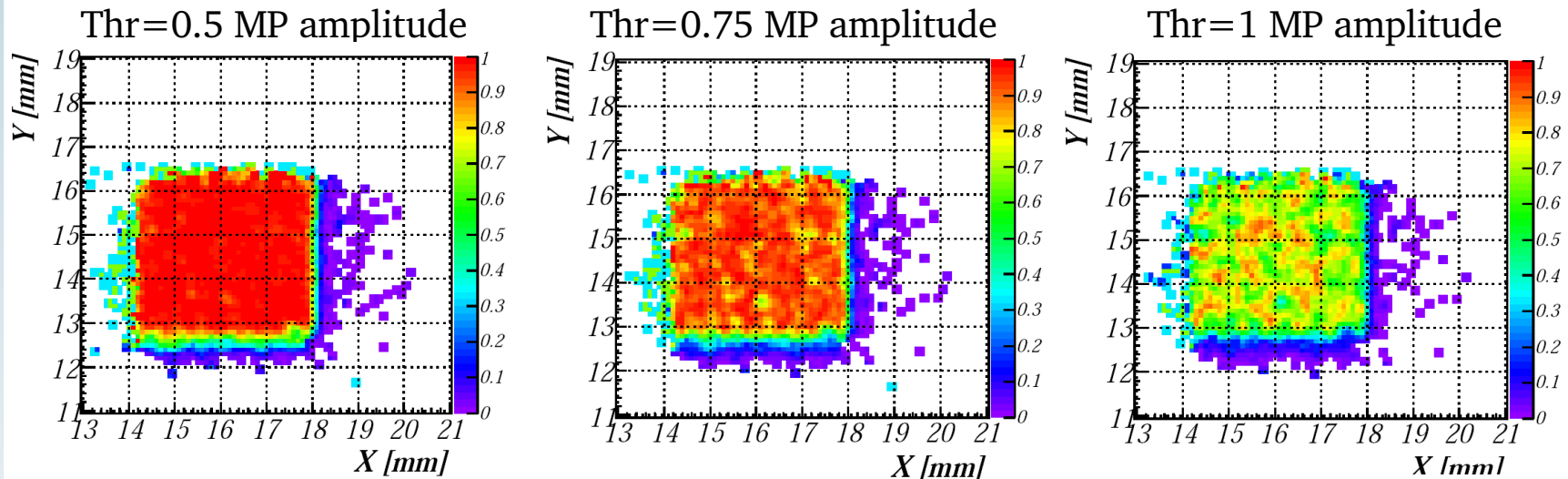
BCM detector modules

# Test Beam at CERN SPS/PS in 2006: xy efficiency scan with analogue signals

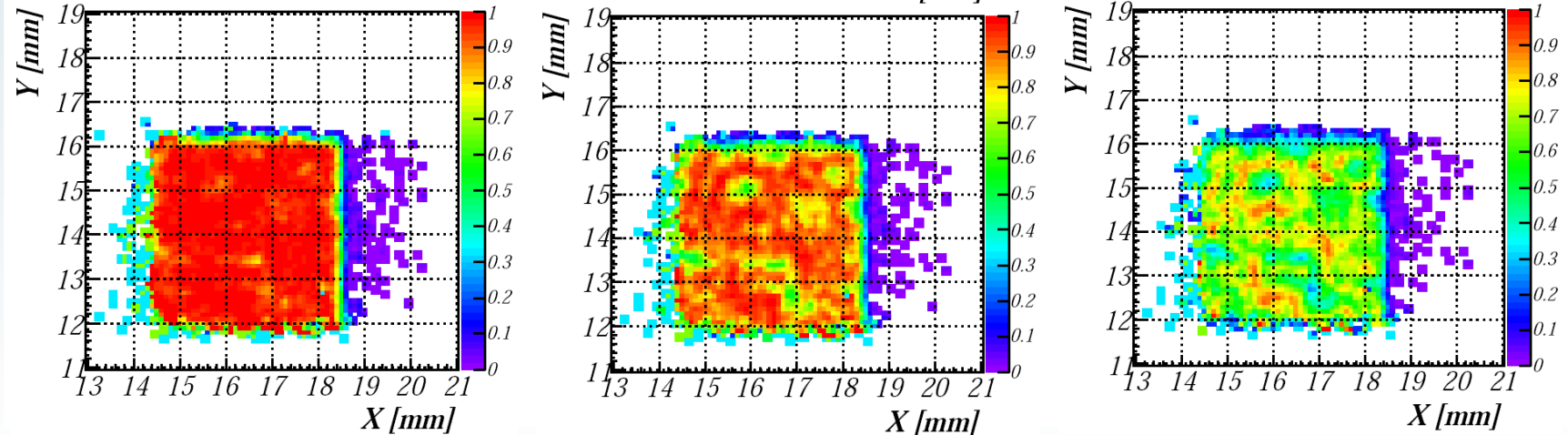
Moving in **steps of 0.1mm** across the xy surface, calculating the fraction of tracks with analogue signal above chosen threshold in  **$0.2 \times 0.2 \text{ mm}^2$  square** at each step:

- ▣ non-uniformity due to the grain structure of the diamonds in assembly

Module  
F408



Module  
F403

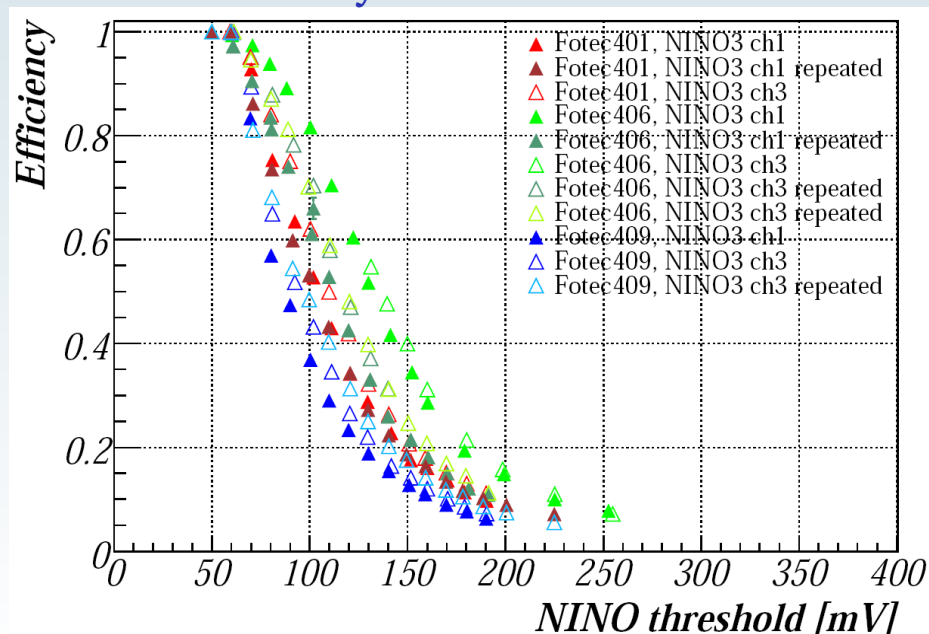


# Test Beam at CERN SPS in 2007

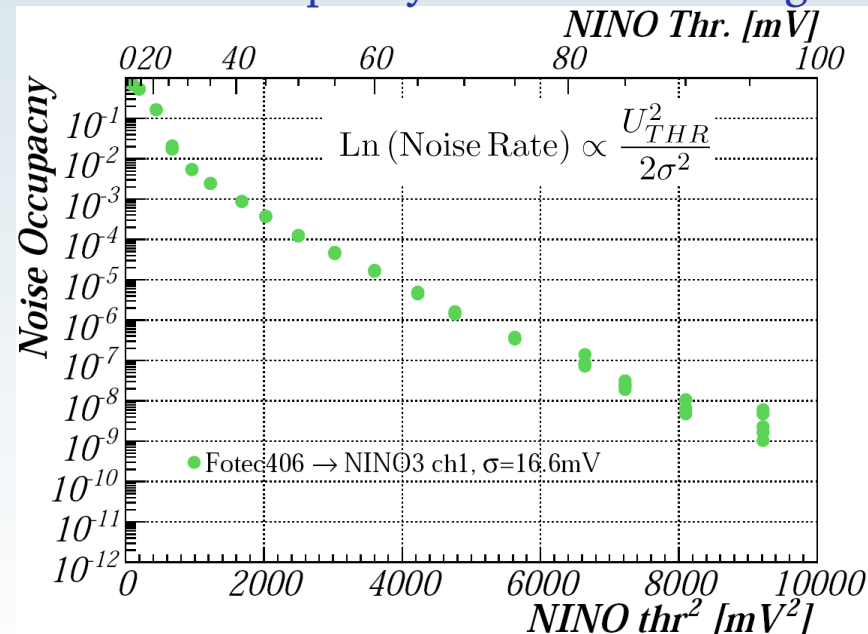
## NINO board performance

- Efficiency curve with triggering on an incident MIP measured by varying the discriminator threshold on NINO board
  - median signal at 100-130mV with different modules
  - final boards:** new amplification added (Mini Circuit GALI-52) to make system more manageable
- Noise rate measured in the lab:
  - with spare detector module (F406, typical of those installed in ATLAS)
  - RMS noise  $\sigma=17\text{mV}$ , median signal  $\approx 125\text{mV}$  → median S/N  $\approx 7.3$

1MIP Efficiency



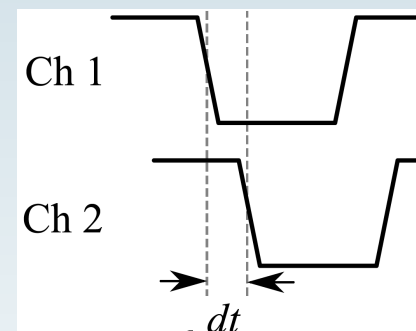
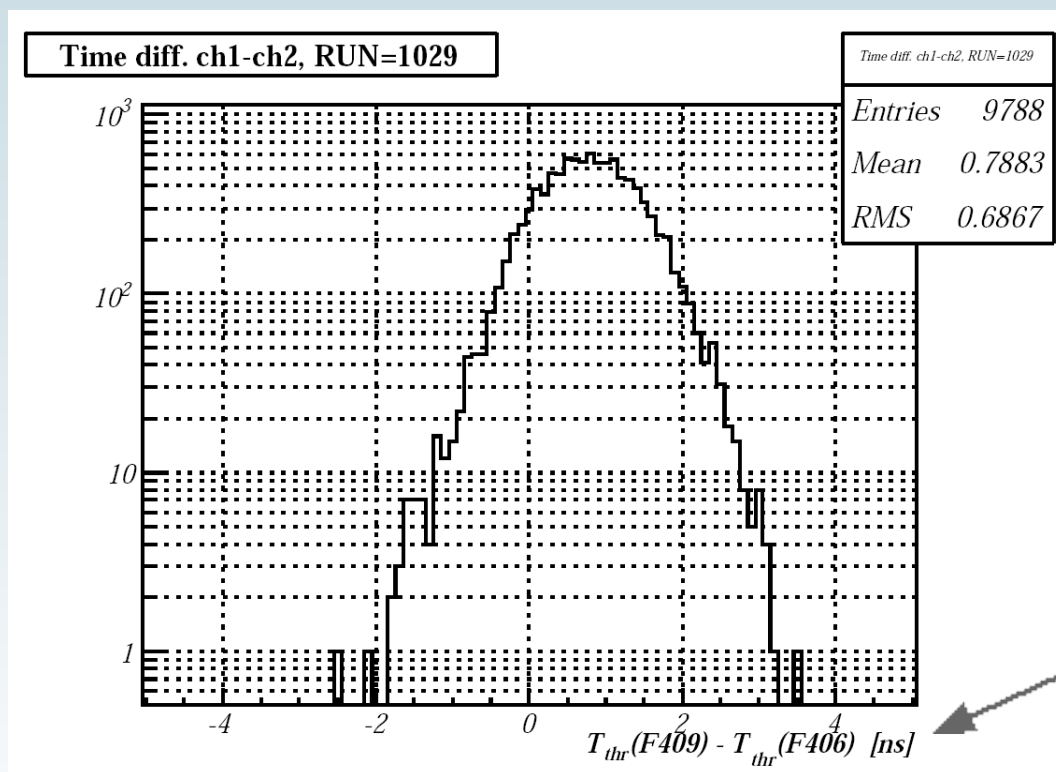
Noise Occupancy in bunch crossing



# Test Beam at CERN SPS in 2007

## Timing resolution after TOT

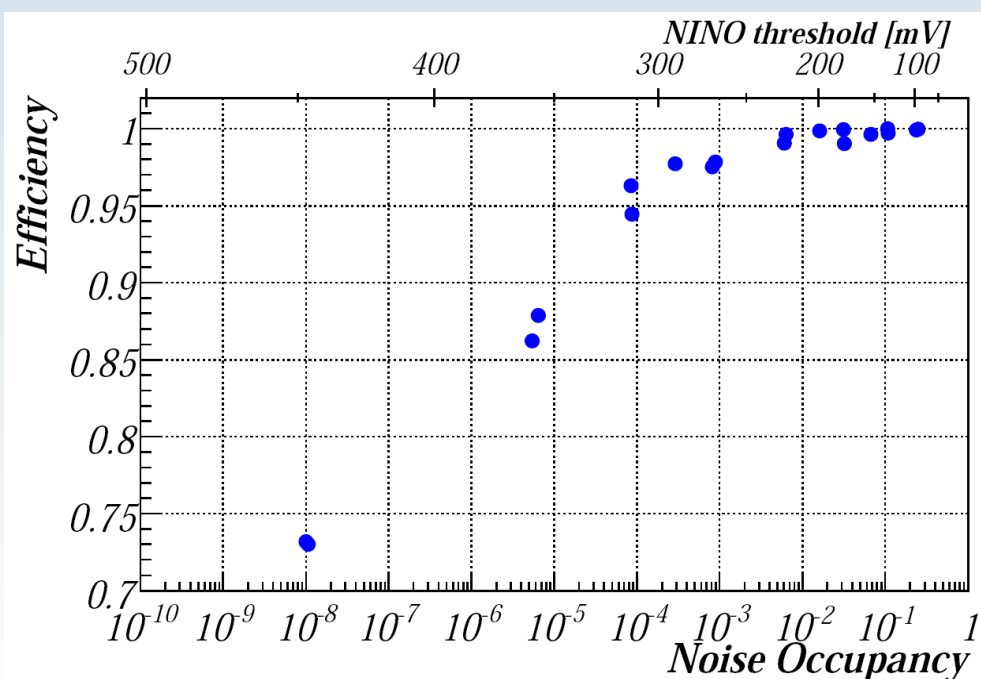
- ▣ Calculated time difference between NINO pulses
- ▣ RMS of time difference distributions below 1.1ns for scanned threshold range  
→ time resolution for one module < 780ps





# Performance of final NINO boards: Efficiency, Noise Rate

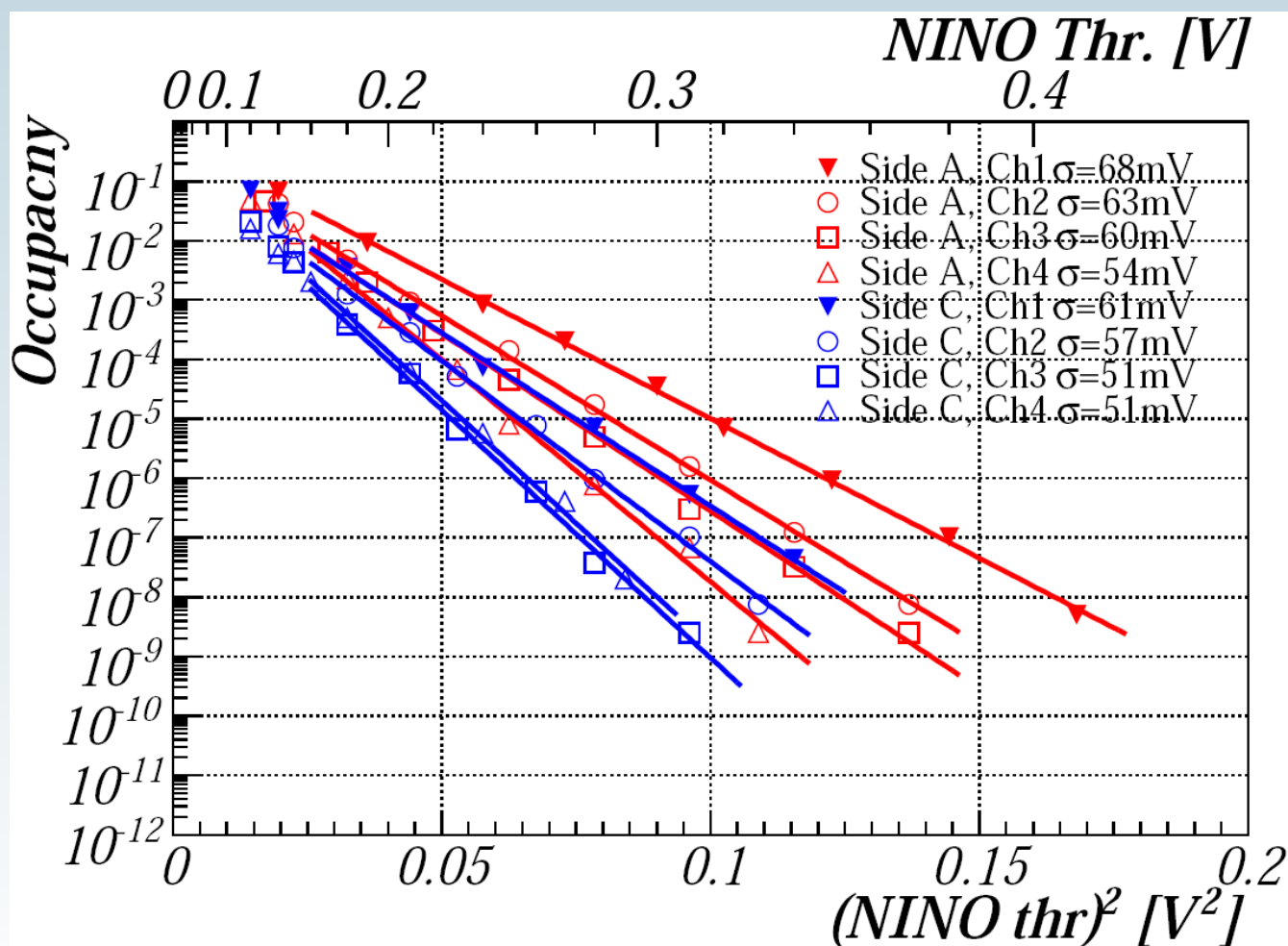
- Final NINO boards: with additional **amplification**
- Noise RMS** estimated from noise rate measurement in lab with spare final NINO board and module F406  $\sigma=75\text{mV}$
- Efficiency** curve measured with spare NINO board and module F406
  - $^{90}\text{Sr}$  source, trigger on BCM detector module signal (**non MIP** efficiency curve)
  - measured curve for final board **scaled to curve for 1MIP** (scaling factor calculated by comparing test beam and  $^{90}\text{Sr}$  measurements obtained for the board tested in test beam):  
median efficiency  $\approx 590\text{mV}$ , median  $S/N \approx 7.9$



- 1MIP efficiency versus noise occupancy (noise rate scaled to 25ns interval – bunch crossing in ATLAS)
  - efficiency 0.95 – 0.99 for occupancies  $10^{-3}$ – $10^{-4}$
- The exact level of fake rate depends on what kind of logical combination of signals will be used in ATLAS

# Performance of installed NINO boards

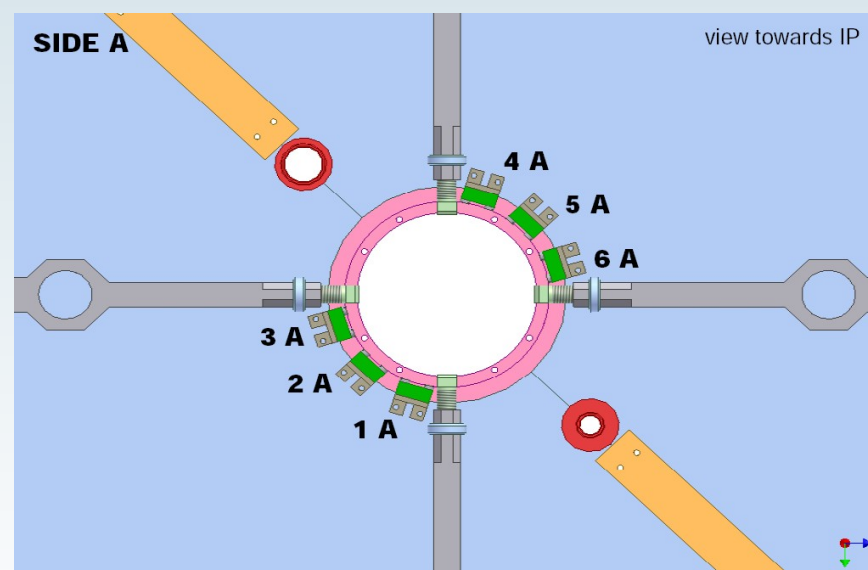
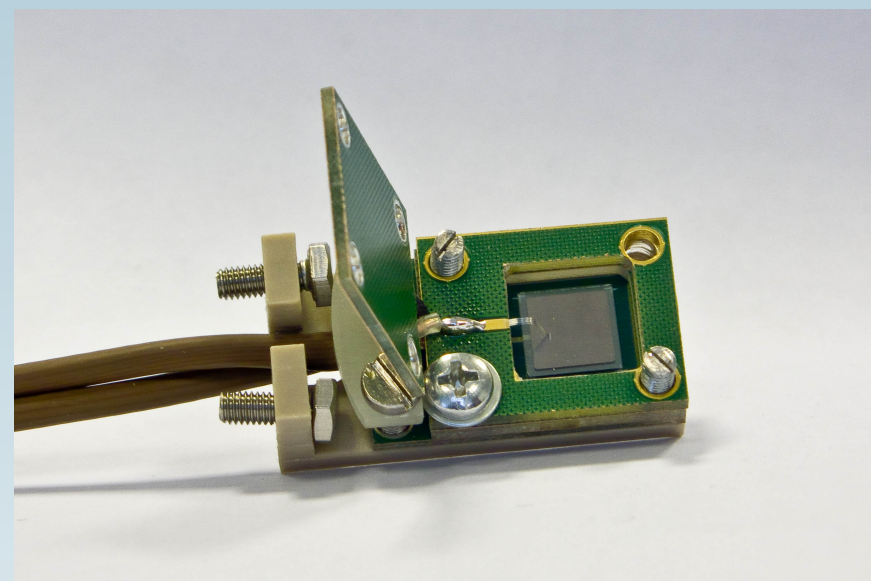
Noise rate measured in ATLAS pit (after installation of NINO boards in ATLAS)



# BLM - Redundant System

## ▣ BLM – Beam Loss Monitor

- ▣ Mostly copied from BLM system installed in BaBar
- ▣ **Sensors:**
  - ▣ one pCVD  $8 \times 8 \text{ mm}^2$  diamond,  $500 \mu\text{m}$  thick.  
metallization  $7 \times 7 \text{ mm}^2$
  - ▣ operated at +500V
  - ▣ current @500V typically  $< 1\text{-}2 \text{ pA}$
- ▣ **12 diamonds** (6+6) installed on Inner Detector End Plate at pixel PP1 in May 2008
- ▣ 12m coax to PP2 (radiation tolerant BLM cards)
- ▣ **Digitization of ionization current** in diamond over  $40 \mu\text{s}$ , converted to frequency at PP2 (LHC CFC cards, radiation tolerant)
- ▣ **Optical transmission** to USA15 counting room, recorded by Xilinx FPGA
- ▣ Use standalone in case of BCM troubles, otherwise complementary information



# Summary

- ▣ ATLAS BCM will monitor beam conditions close to IP using **TOF measurement**
- ▣ **pCVD diamonds** as sensor material
  - ▣ 2 diamonds in a back-to-back configuration
  - ▣ at  $45^\circ$  towards the beam
- ▣ Test beam and lab results indicated **operable system**
  - ▣ rise time, pulse width, S/N meet criteria
  - ▣ efficiency, noise occupancy acceptable
- ▣ **Status:**
  - ▣ BCM and BLM (redundant system) installed
  - ▣ focus shifted towards development of FPGA algorithms

