Aerogel RICH Counter at the Belle II Detector

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Abstract

We report on the design, operation, and performance of a novel proximity-focusing Ring Imaging Cherenkov (RICH) detector equipped with a multilayer focusing aerogel radiator, developed for the forward region of the Belle II spectrometer at the SuperKEKB e^+e^- collider. The system achieves effective separation of charged pions, kaons, and protons across the full kinematic range of the experiment, from 0.5 GeV/c to 4 GeV/c. To date, the detector has been successfully operated in data taking, contributing to the collection and analysis of nearly 600 fb⁻¹ of Belle II collision data.

Keywords: RICH, aerogel radiator, HAPD, Belle II, ARICH

1. Introduction

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The Belle II experiment, located in Tsukuba, Japan, is ded- 19 icated to precision measurements of rare decays of B and D 20 mesons and τ leptons. Following the highly successful opera- 21 tion of the original Belle spectrometer between 1999 and 2010, 22 and numerous landmark physics results [1], the pursuit of possi- 23 ble deviations from the Standard Model in extremely rare decay 24 channels necessitated a two-order-of-magnitude increase in the 25 recorded data sample.

To achieve this goal, the KEKB e^+e^- collider underwent a ²⁷ major upgrade, resulting in the construction of the SuperKEKB ²⁸ accelerator, designed to operate at event rates approximately 30 ²⁹ times higher than its predecessor and to ultimately deliver an ³⁰ integrated luminosity of 50 ab⁻¹ [2]. The substantially higher ³¹ interaction rates and corresponding background levels required ³² a comprehensive upgrade of the Belle spectrometer, with only ³³

the mechanical structure and the 1.5 T solenoid magnet retained from the original detector [3, 4, 5].

To meet its physics objectives, the Belle II experiment requires highly efficient kaon–pion separation for charged particles with momenta up to 4 GeV/c, achieved using two dedicated subsystems based on Cherenkov photon detection. Particle identification in the barrel region of the spectrometer is provided by the Time-of-Propagation (TOP) counter [6] while the Aerogel Ring Imaging Cherenkov (ARICH) detector—described in detail in this paper—was developed to distinguish kaons from pions across most of their momentum range in the forward (end-cap) region of the Belle II spectrometer (Fig. 1).

The ARICH is a proximity-focusing Ring Imaging Cherenkov (RICH) counter (Fig. 2) comprising several key components: a radiator, where charged particles emit Cherenkov photons; an expansion volume, allowing the photons to form ring images on the detection plane; an array of position-sensitive photon detectors, capable of single-photon detection in a strong magnetic field with high efficiency and excellent two-dimensional spatial resolution; and a readout system that records and processes the detected signals.

The remainder of this paper is organized as follows. Sections 2-9 discuss the design considerations and the main de-

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tector components, including the aerogel radiator, photon sen- 94 sors, readout electronics, mechanical structure, and associated 95 services. Section 10 outlines the simulation and reconstruc- 96 tion methods, and Section 11 presents the performance results 97 obtained during operation with colliding electron and positron 98 beams.

2. Design choices

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The following considerations guided the design choices for the ARICH detector. The kinematic range of the Belle II experiment — covering pion and kaon momenta from 0.5 GeV/ c^{100} to 4 GeV/c — requires the use of aerogel radiators with a refractive index of approximately 1.05 (Fig. 3). To achieve the desired performance, a sufficient number of Cherenkov photons ($N \approx 10$) must be detected for each ring image, at least for one of the particle species. This requirement determines the total thickness of the aerogel radiator, which must be several centimeters.

The Cherenkov angle resolution needed for 3σ pion-kaon¹¹³ separation ($\sigma_{\rm track}\approx 7$ mrad) can be obtained only if the expansion gap is about 20 cm and the photon detector granularity is on the order of a few millimeters.

A proof-of-principle prototype demonstrated excellent performance in both laboratory and beam tests [7]. However, two
major challenges remained: increasing the number of detected
Cherenkov photons, and developing a single-photon detector
capable of reliable operation in the 1.5 T magnetic field of the
Belle II spectrometer. Both challenges were successfully adtessed, as discussed below.

The key performance parameter of a RICH counter is the 124 Cherenkov angle resolution per charged particle, $\sigma_{\rm track} = 125 \ \sigma_{\theta} / \sqrt{N}$, where σ_{θ} is the single photon resolution and N is the 126 number of detected photons. Increasing the radiator thickness 127 enhances photon statistics but degrades single-photon resolution in a proximity-focusing RICH due to emission-point uncertainty. Within the spatial constraints of the Belle II spectrom-130 eter, the smallest $\sigma_{\rm track}$ is achieved with a radiator thickness of 131 about 20 mm [7, 8]. However, in this configuration the photon 132 yield is insufficient for the required separation power.

This limitation can be overcome using a non-homogeneous, multilayer aerogel radiator [8, 9, 10, 11]. By selecting differ-135 ent refractive indices for consecutive aerogel layers, the corresponding Cherenkov rings can be made to overlap on the photon-detector plane (Fig. 2) [8, 9]. This creates an effective focusing of photons within the radiator, significantly reducing 137 the spread arising from emission-point uncertainty. Such fine control of the refractive index is uniquely feasible with aerogel, which can be produced with indices in the range 1.01 - 1.2 [12]. Beam-test results comparing two 4 cm-thick radiators — one with uniform refractive index (n = 1.046) and the other with a dual-layer focusing configuration ($n_1 = 1.046$, $n_2 = 1.056$) [13] — clearly demonstrate the benefit of this approach. As can be seen in Fig. 4, the single-photon angular resolution improves from $\sigma_{\theta} = 20.7$ mrad in the uniform case to $\sigma_{\theta} = 14.3$ mrad

for the dual-layer radiator, while maintaining a similar photon yield in both configurations ⁴.

The second primary design requirement concerned the development of a photon sensor capable of detecting single photons in a strong magnetic field and withstanding the expected radiation load, corresponding to a 1 MeV-neutron equivalent fluence of about 10¹² n cm⁻² over the experiment's lifetime. This challenge was met with the Hybrid Avalanche Photodetector (HAPD) developed by Hamamatsu Photonics, a proximity-focusing device selected as the baseline Cherenkov light sensor. Two alternative sensor technologies were also successfully evaluated: a multi-channel microchannel-plate photomultiplier tube (MCP-PMT) [14, 15, 16, 17] and a silicon photomultiplier (SiPM)-based photon detector [18, 19].

Another important consideration in the detector design is the loss of photons at the side walls of the ARICH vessel (Fig. 5). This effect is mitigated by installing planar mirrors that reflect photons back into the active region, thereby improving the overall Cherenkov light collection efficiency.

3. Aerogel

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The radiator plane comprises two layers of wedge-shaped hydrophobic aerogel tiles with nominal refractive indices of n = 1.045 in the first and n = 1.055 in the second layer. As discussed in Sec. 2, they are chosen in such a way that Cherenkov rings from the first and second layers overlap on the detector plane (Fig. 2) for the relevant kinematic range and a wide range of incidence angles [9].

The aerogel tiles, totaling 124 for each refractive index, were fabricated using the super-critical drying method [20] at the Japan Fine Ceramics Center. As shown in Fig. 6, the radiator system is segmented into four rings, each equipped with a separate type of wedge-shaped tiles. The tiles were cut out of square-shaped $180 \times 180 \times 20 \text{ mm}^3$ pieces of aerogel using a water-jet cutting device.

To achieve a good PID performance, the aerogel tiles should be physically undamaged (with no cracks or chips) and should exhibit good transparency. Figures 7, 8, and 9 show the distributions of the refractive indices and transmission lengths of the aerogel tiles from the mass production.

The refractive index of the tiles was controlled with appropriate precision so that the difference in the refractive index of the downstream and upstream tile pairs, $n_2 - n_1 = 0.0098 \pm 0.0002$ (Fig. 9), is well within the optimal interval [9].

4. Photon detector - HAPD

As the sensor for single Cherenkov photons, a hybrid avalanche photodetector (HAPD) (Fig. 10) is used, where pho-

⁴An alternative geometry was also studied with a reversed order of the two aerogel tiles that would produce two separate rings [8]; while interesting, this de-focusing configuration was not further pursued because, with two separate rings that cover a larger area of the photon detector than a single ring, the background level would increase and could therefore deteriorate the particle identification performance.

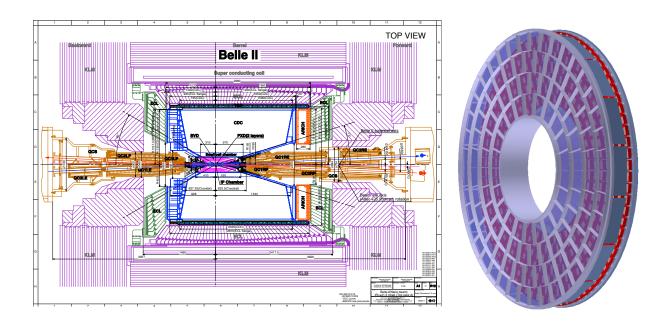


Figure 1: The Belle II spectrometer (left) and the geometry of the ARICH detector (right) with its main components, aerogel radiator (depicted in blue) and photo-sensors (in dark red).

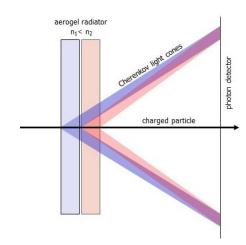


Figure 2: Proximity focusing RICH with a dual radiator in the focusing configuration.

toelectrons are accelerated in a static electric field and are de-¹⁵⁶ tected with a segmented avalanche photodiode (APD). The pho-¹⁵⁷ ton detector plane is covered with 420 HAPDs, arranged in¹⁵⁸ seven concentric rings as shown in Fig. 6.

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The HAPD employed in the Belle II ARICH detector has ¹⁶⁰ been developed in collaboration with Hamamatsu Photon-¹⁶¹ ics [23, 22, 21]. It has outer dimensions of $7.3 \times 7.3 \times 2.0$ cm³, ¹⁶² a bi-alkali photocathode on the inner side of the quartz win-¹⁶³ dow, and four pixelated avalanche photodiodes (APDs) at the ¹⁶⁴ bottom of the tube, each with 36 5×5 mm² channels (Fig. 10). ¹⁶⁵ The pixel size is 4.9×4.9 mm², and the gap between pixels is ¹⁶⁶ 0.2 mm within the APD; APDs are separated by 1.5 mm. The ¹⁶⁷ active area is about 65% of the HAPD package size. The total ¹⁶⁸ gain of about 3×10^4 , comprised of the bombardment gain and ¹⁶⁹

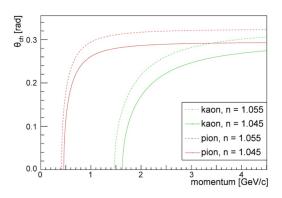


Figure 3: Cherenkov angle for pions and kaons for two refractive indices of the Cherenkov radiator, 1.045 and 1.055.

the gain in the APD, is provided by the high voltage of 6 kV applied to the tube; the bias voltage applied to the APD is such that the gain in the APD amounts to 30. The quantum efficiency (Q.E.) of the photocathode at 400 nm is between $\approx 25\%$ and $\approx 40\%$ as can be seen in Fig. 11. The photoelectron detection efficiency is around 90%.

Following a set of radiation tolerance tests [24] with neutrons and gamma rays, sensor production was optimized (thicknesses of p and p^+ layers, and an additional intermediate electrode). The final version of tested samples retained the required performance at the 1 MeV-neutron equivalent fluence of 10^{12} n cm⁻², expected in the lifetime of the experiment. Another optimization of the sensor production (getter re-activation in the vacuum tube) was carried out to mitigate instabilities in the form of discharges when operated in the 1.5 T magnetic field [25].

The high-voltage system for the HAPDs consists of 7 CAEN

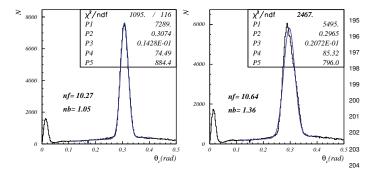


Figure 4: Proximity focusing RICH, proof of principle in a beam test: the ac- 206 cumulated distribution of Cherenkov photon hits depending on the correspond- 207 ing Cherenkov angle for a 4 cm homogeneous radiator (right) and for a focusing 208 configuration with two 2 cm thick layers with $n_1 = 1.046$, $n_2 = 1.056$ (left) [13].

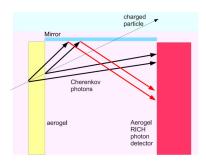


Figure 5: Recovery of photons emitted at the outer edge of the ARICH detector acceptance: planar mirrors on the side wall of the ARICH vessel.

SY4527 crates, 45 CAEN A7042P 48-channel 500 V common²²⁴ floating return boards, supplying four bias voltages and one²²⁵ guard voltage for each of the 420 HAPDs, and 28 CAEN A1590²²⁶ - AG590 16-channel 9 kV boards supplying 420 high voltages.²²⁷

5. Readout Electronics

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A total of 60480 readout channels are needed to equip²³⁰ 420 HAPDs, with a single bit of on/off hit information for each channel. As shown in Fig. 14, a front-end board (FEB)²³¹ with 4 ASICs and an FPGA (Xilinx Spartan 6, XC6SLX45-²³² 2FGG484) is attached to each HAPD. The 36-channel ASIC,²³³ named SA03, was developed in the X-FAB 0.35 μ m process²³⁴ technology in collaboration with Japan Aerospace Exploration²³⁵ Agency (JAXA).

The ASIC consists of a preamplifier with a variable gain be-²³⁷ tween 17 mV/fC and 56 mV/fC, a shaper with a shaping time²³⁸ that can be set to 170 ns, 210 ns, 240 ns, and 350 ns, and a dis-²³⁹ criminator [26]. It processes the analog signals from the HAPD.²⁴⁰ A common threshold voltage is applied to the discriminator of²⁴¹ the ASIC, while the baseline voltage of each channel can be ad-²⁴² justed so that, effectively, the threshold of each channel can be²⁴³ set independently.

The digital signals, output from ASICs, are processed in the²⁴⁵ FPGA [26, 27], and sent to the back-end electronics board²⁴⁶ ('merger') located behind the front-end boards using parallel²⁴⁷ cables. The merger board, equipped with another FPGA (Xil-²⁴⁸

inx Virtex 5, XC5VLX50T-1FFG665C), collects data from 5 to 6 front-end boards, performs zero suppression to reduce data size, and transfers them to the central DAQ through the Belle2Link [28]. The slow control, such as the read and write of the parameters in the ASICs, FEBs, and in the merger, is realized through the Belle2Link. The merger also receives the first-level (L1) trigger signal and distributes it to the front-end boards.

The hit information from the HAPD sensors is read out in four adjacent time intervals. In the standard configuration, one timing bin corresponds to 125.6 ns so that the time window for the readout is 502.4 ns. The middle two timing bins are adjusted to the correct timing with respect to the L1 trigger, and the two side bins are used to estimate the background level on an event-by-event basis (see also Sec. 9.2).

The front-end readout board and merger board were designed to withstand a 1 MeV-neutron equivalent fluence of 10^{12} n/cm² and a gamma radiation dose of 100 Gy, as expected over the lifetime of the Belle II spectrometer.

The low-voltage supply system for the read-out electronics is comprised of two Wiener MPOD systems and 12 low-voltage Wiener MPV8008LI modules (with 8 channels, output voltage 0 V-8 V at 5A, 40 W per channel, floating with < 2 mVpp ripple). These modules provide supply voltages of +3.8 V, +2 V, and -2 V to the 420 front-end boards and +1.5 V and +3.8 V to the 72 merger cards. From the three supply voltages at a front-end board, a reference voltage of 1.25 V is generated by a diode, while other operating voltages are provided by low-dropout regulators (LDOs). For monitoring purposes, an analog-to-digital converter (ADC) digitizes the various internal voltage levels, which are selectable via a multiplexer. The discriminator threshold level is adjusted using a digital potentiometer. The board is also equipped with an internal 42 MHz oscillator to clock the FPGA; an external clock is used during data taking operation with the Belle II detector.

5.1. Firmware Design

The firmware system integrates a 64-bit instruction decoder, a data sender, a command receiver, and a response sender. Instructions are received via a unidirectional asynchronous Serial Peripheral Interface (SPI). The response to each command is returned encoded in a response word through a separate, dedicated one-way SPI channel. A trigger signal activates the data encoder, which then transmits data to the merger board via another one-way SPI.

Each hardware peripheral device is managed by a driver, which is activated by the instruction decoder. Additionally, a data register controls the mode of operation, sampling rates, and encoder frequencies. The unique FPGA device identifier (DNA) is used to identify the board.

To mitigate the impact of single-event upsets (SEUs) at the FPGAs of the FEBs, a scrubber of the configuration data of the FEBs is implemented in the firmware of the merger [30]. The scrubber monitors the SEUs at FPGAs of FEBs and corrects them by a partial reconfiguration.

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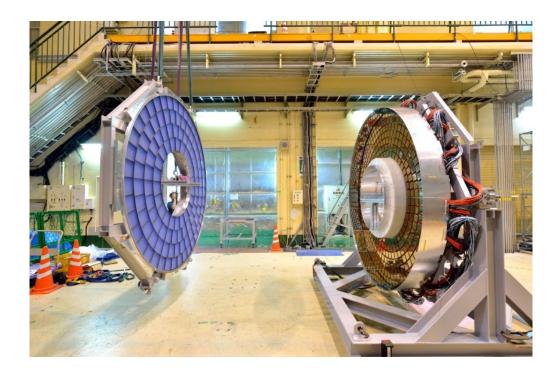


Figure 6: Two halves of the ARICH detector: radiator plane covered with two layers of aerogel tiles (left), photon detector plane covered with 420 HAPDs and planar mirrors mounted on the side wall (right), before the two were joined to form a single vessel.

6. Mechanical structure and services

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The ARICH detector components are mounted inside a donut-shaped vessel as shown in Fig. 6. The vessel is com-280 prised of two halves, one housing the aerogel radiator system, 281 and the other the photon detectors with the read-out electron-282 ics. The total weight of approximately 400 kg is supported by 283 two main mechanical components of the inner cylinder and the 284 plate on which the HAPDs are mounted.

On the photon detector side, the HAPDs and the associated read-out electronics are mounted on an aluminum support structure, comprised of six azimuthal sectors. The support structure also provides a common electrical ground for the read-out elec-289 tronics and sensors. It also conducts heat from the front-end boards to the cooling system. Each of the six detector sectors 18 cooled by water flowing through a 5 m long aluminum pipe with 6 mm outer diameter and 1 mm thick walls as shown in 193 Fig. 17. With a water flow of 1 l/min per sector and the output-294 input temperature difference of $\approx 2^{\circ}$ C enough cooling is pro-295 vided to extract ≈ 130 W of heat from each of the sectors. With 296 this arrangement, the temperature of FPGAs is maintained at 297 approximately 40°C (Fig. 18).

On the inside of the outer wall of the ARICH vessel, 18 pla-299 nar mirrors are mounted to reflect the photons that would oth-300 erwise be lost back to the photo-sensitive area (Fig. 5), as dis-301 cussed in Sec. 2. The mirrors are 13.1 cm wide and 37.3 cm long, with a reflectivity exceeding 85% in the wavelength interval between 250 nm and 600 nm. The front surface technology is used to reflect photons from the surface coating, to prevent303 the emission of additional Cherenkov photons in the glass.

7. Construction

7.1. Quality assurance of the components

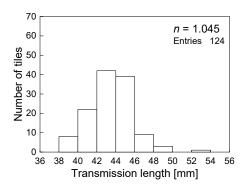
All ARICH components underwent several quality assessment (QA) measurements before assembly. The operational parameters of the photo sensors were determined, including the operating values of high voltage and APD bias voltages, as well as measurements of leakage currents, quantum efficiency and a performance test in a magnetic field. Voltages and currents on the front-end electronics were monitored and the response of each channel was tested. Currents through high voltage distribution boards were measured with an applied voltage of 9 kV. If all components met a satisfactory quality and response, the final module, consisting of an HAPD, a front-end board and a high-voltage distribution board (Fig. 13), was assembled and re-tested.

We scanned the sensor surface over the channel centers and measured its response to short, low-intensity laser pulses at different discriminator values (Fig. 19). From this measurement, the gain of individual channels can be extracted. We anticipate the gain will slowly decrease during operation due to irradiation, requiring adjustments to the front-end board ASIC gain and shaping time to compensate.

We also measured and monitored the refractive indices of aerogel tiles and their transmission lengths (Figs. 7, 8, 9).

7.2. Construction

During the quality assurance of the photosensors we observed a position dependence of the quantum efficiency of the



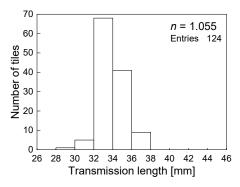


Figure 7: Aerogel properties of the installed tiles: the distribution over the transmission length at 400 nm for the upstream (top) and downstream tiles (bottom).

photo sensors as displayed in Fig. 12. The variation is significant, since the production specification required only the minimal quantum efficiency value. To equalize the ARICH detector performance across the whole active surface, we randomly selected the mounting positions of the HAPDs.

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Since the measurements of the properties of aerogel tiles showed minimal variations, the tile pairs were randomly distributed in the mounting frame during installation. The aerogel tiles are fixed to the structure of one of the halves of the mechanical structure of the ARICH detector using very thin carbon fiber strings to keep them in place when the detector is in the vertical position. Photodetector modules were mounted to the aluminum structure of the other detector half. The cables

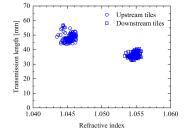


Figure 8: Aerogel properties of the installed tiles. The horizontal axis shows the refractive index, while the vertical axis shows the transmission length at 400 nm.

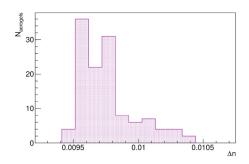
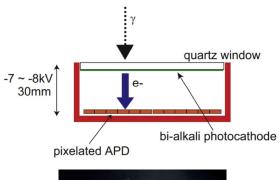


Figure 9: Aerogel properties of the installed tiles: the difference in refractive index between downstream and upstream tiles.



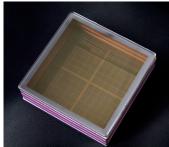


Figure 10: HAPD single-photon sensor; top: the principle of operation [21, 22], bottom: a photograph of the sensor.

for power supply and data transfer were custom-made primarily on-site. The eighteen planar mirrors were installed at the sides of the detector plane.

The two halves of the ARICH detector were combined, and aluminum panels were attached at the edges, as seen in Fig. 20.

8. Slow control system

The Belle II ARICH slow control system [31] comprises four subsystems. The High Voltage System controls and monitors the HAPD high voltages, the Low Voltage Control System manages the voltage supplies to the readout electronics, the Environmental Monitor monitors the detector temperature, and the Front-End Board Control System uploads firmware, sets parameters of the readout chip, controls temperature, and manages the single event upset mitigation controller [30].

The control daemons communicate with other processes using the common Belle II Belle2Link [28] and the Network

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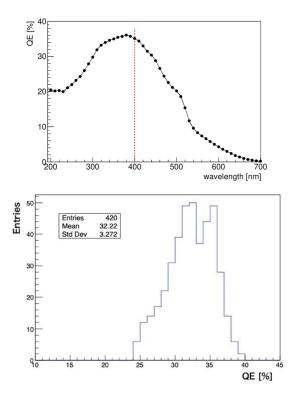


Figure 11: HAPD single-photon sensor; top: quantum efficiency of a typical sensor as a function of wavelength, the red line indicating the reference wavelength of 400 nm; bottom: quantum efficiency at 400 nm for all installed HAPDs.

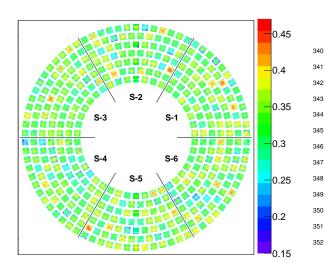


Figure 12: ARICH photon detector plane: quantum efficiency at 400 nm as a struction of the photon impact coordinate.

Shared Memory 2 (NSM2) protocol. They accept requests to senable and disable supply channels and adjust hardware set-sen tings. Configuration settings are loaded from a common Belle II database, allowing for flexible and controlled value changes. The slow control system also continuously monitors voltage, securrent, and other detector parameters, such as temperatures

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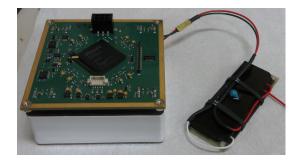


Figure 13: HAPD read-out and high voltage supply: the front-end board on top of the HAPD and the high voltage supply board; when installed in the detector, the high voltage supply board gets mounted above the front-end board.

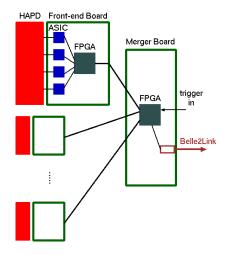


Figure 14: Readout electronics for ARICH: schematics.

and the number of hits. The values of the monitored parameters are regularly stored in the EPICS Archiver Appliance of the Belle II experiment [32], and only significant changes from previous readings are saved. This approach reduces the need to store large amounts of data from over 15,000 monitoring variables. The slow control graphical user interfaces implemented in Control System Studio [33, 34] visualise the current status and history of the slow control variables in an organised manner (Fig. 21). Finally we note that a special tool was developed with a graphical interface which visualises the connections between different detector parts. This feature was crucial during the installation and commissioning phases as well as during operation for identifying malfunctioning parts.

8.1. High Voltage and Low Voltage Systems

The high-voltage (HV) system is controlled by HV daemons that communicate with the hardware using the CAEN HV wrapper library. To minimize discharge risks, all 6 HV channels supplying a given HAPD are synchronous and follow well-defined transitions between different system states. Hardware interlocks ensure safe operation. Over 10,000 parameters are read from the high-voltage boards every ten seconds and recorded in the archiver database. For instance, the history of bias currents helps estimate background irradiation levels on different detector parts (Fig. 22).

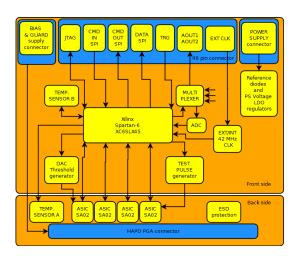


Figure 15: Functional schematic of the front-end board [29] with four custom ASICs on the HAPD side, and a Xilinx Spartan-6 FPGA on the other side of the board.



Figure 16: Readout electronics: merger board (top) and mounted merger boards with services (bottom).

The low-voltage supply slow control system is controlled by₃₉₃ a separate deamon that communicates with the Wiener MPOD₃₉₄ crate controller using the Simple Network Management Proto-₃₉₅ col (SNMP). In the same manner as the high voltage deamon, it₃₉₆ ensures that the groups of voltages supplying a group of HAPD₃₉₇ baseboards and merger boards are switch together.

8.2. Data quality monitors

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Additional processes continuously extract key parameters⁴⁰¹ from the reconstruction running online on a fraction of the data.⁴⁰² These parameters include the Cherenkov angle of high momen-⁴⁰³ tum tracks, the number of hits per track, the number of hot and⁴⁰⁴

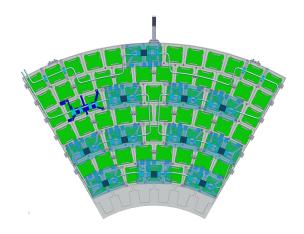


Figure 17: Cooling system of the read-out electronics: cooling pipes are in thermal contact with the merger support elements (dark blue) that are in thermal contact with FPGAs (black squares) on the merger boards (transparent blue), merger board ground-plane, and the main aluminum support structure (in grey). The cooling of the FE boards (in green) is provided through the thermal contact with the main aluminum structure. One of the merger boards was removed to reveal the associated support element (in dark blue). For other mergers, the PCB is displayed transparently, allowing the FPGAs to be visible in black and the connectors in blue.

dead channels, and the temporal distribution of hits. The temporal changes of these parameters are monitored via various web interfaces (Figs. 25 and 28).

8.3. Environmental monitors

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The data acquisition controller implements a process that controls the parameter settings of the readout cards and monitors their basic functionality, including readings of supply voltages, temperatures, and single-event upset (SEU) counts (Figs. 18 and 23). Additionally, it monitors the temperature of inlet and outlet water cooling pipes and the status of the cooling unit. Additional temperature sensors at various parts of the detector are read from a common Belle II environmental monitoring system.

9. Commissioning and Operation

9.1. Commissioning

The ARICH detector commissioning phase began early in 2018, concurrent with the commissioning of all other Belle II spectrometer components. During this phase, the detector proved to operate reliably.

Before the start of data acquisition, the front-end boards had to be programmed to set a common gain, discrimination threshold, and channel-dependent offsets for each ASIC. An example of a calibration of the channel offsets is shown in Fig. 24. Offsets calculated from the upper plot were uploaded to the detector, allowing one common threshold to discriminate between hit and non-hit channels. Offsets calculated from the upper plot were uploaded to the detector, allowing one common threshold to discriminate between hit and non-hit channels.

The initial commissioning revealed that the cooling system required an upgrade to enhance its performance through a more

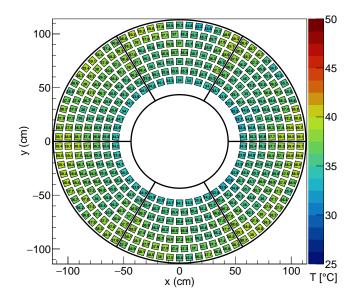


Figure 18: Temperature of the front-end boards during regular data taking operation.

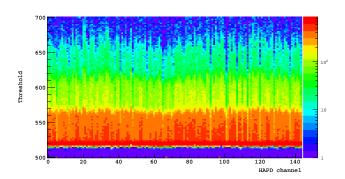


Figure 19: Threshold scan of the 144 channels of a HAPD: the responses of pads illuminated by short laser light pulses at different threshold voltages.

efficient thermal coupling to the read-out electronics boards. This upgrade was carried out during the summer shutdown in 2018. By the end of 2018, the commissioning phase was completed, and was followed by the first physics data-taking runs in the spring of 2019.

9.2. Operation

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The ARICH detector proved to run stably from the commis-427 sioning phase onward. As already discussed above, various parameters are continuously monitored to ensure a stable performance and react in case of deviations in performance.

To monitor the performance of the photo-sensors, an LED 430 light ($\lambda = 470$ nm) emitted from LEDs and distributed through optical fibers to 90 points in the gaps between the photo-sensors is used on a regular basis. The light is reflected from the aerogel $_{433}$ surface and is spread over the surface covered by HAPDs; it is $_{434}$ used to identify noisy and dead channels, as well as to measure $_{435}$ the relative sensitivity and gain of each channel.

During the acquisition of beam collision data, the quality₄₃₇ of the data is constantly monitored. In the event-based filter,₄₃₈

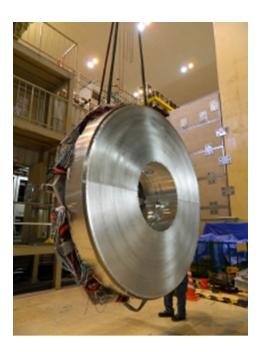


Figure 20: ARICH detector construction: combining the two detector halves.

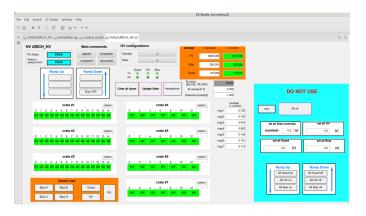


Figure 21: The main graphical user interface for slow control

HAPD sensors with too many hits are rejected. Checks of dead and noisy channels (Figs. 25 and 26) is carried out for each run, and new channels that appear in this list are taken into account in the reconstruction.

As discussed in Sec. 5, the hit information is read out in four adjacent 125.6 ns long time intervals, where the middle two are adjusted to the correct timing with respect to the L1 trigger, and the two side bins are used to estimate the background level on an event-by-event basis (Fig. 27).

We also monitor the overall performance of the detector by checking the two most relevant variables, the Cherenkov angle and the number of detected Cherenkov photons of ultrarelativistic muon tracks (p > 4 GeV/c). As shown in Fig. 28, the detector indeed performs reliably over extended periods of time.

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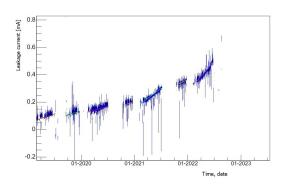


Figure 22: Dark current of one of the 36-channel APDs (one quarter of the HAPD), shown as a function of time; adopted from [35].

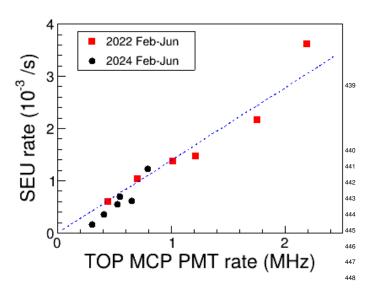
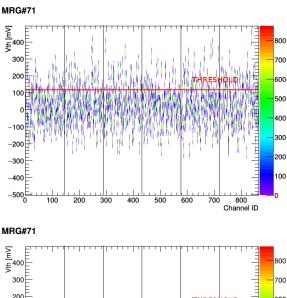


Figure 23: Relation between the SEU rate in ARICH and the hit rate of an MCP- PMT in the TOP detector. Each point corresponds to a period of SuperKEKB⁴⁵⁰ operation (typically 2 weeks) in 2022 and 2024. The dashed line is the fit result₄₅₁ to a linear function. The TOP MCP-PMT rate is known to correlate well with₄₅₂ the SuperKEKB beam background level.



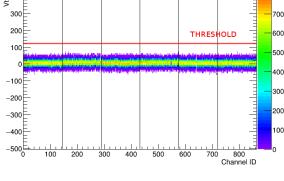


Figure 24: Response of the detector, a threshold scan for each of the channels of a single merger board with six front-end boards connected (corresponding to $6 \times 144 = 864$ channels). Upper plot: non-calibrated offsets, lower plot: threshold scan with calibrated offsets.

10. Simulation and reconstruction

The ARICH simulation and reconstruction software is integrated into Basf2 (Belle Analysis Software Framework 2) [36] which provides a common framework for the Belle II detector simulation, event reconstruction, and data analysis. The code is organized in the form of independent modules (mostly written in C++) that perform a specific task and are included in the main event processing loop using Python-based steering files. For the ARICH detector the basic structure of the event loop is shown in Figure 29. For the simulated data the loop starts with the Geant4 simulation of the event. In the simulation, photon hits on the photon detectors are recorded. At the stage of digitization, these hits are converted to the so-called digits, which correspond to the actual output from the detector (i.e., containing only hit channel numbers). For the analysis of measured data, the event loop starts with the collection of digits, obtained directly from the raw data. Finally, the ARICH reconstruction module uses the collection of tracks impacting on the aerogel (obtained from the Belle II tracking system) and the collection of photon hits to calculate the PID likelihoods for each track.

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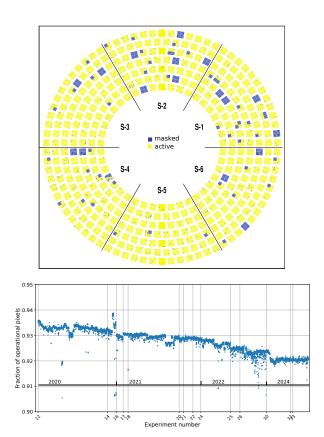


Figure 25: Masked channels: distribution over the photon detector at the beginning of Run 2 in December 2023 (top); variation of the number of masked channels with time (bottom).

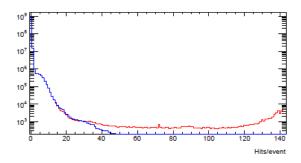


Figure 26: Number of hits per sensor per event. All sensor hits (red) and accepted hits (blue).

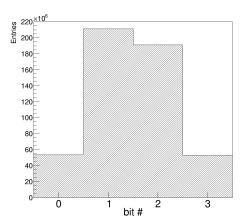


Figure 27: Timing alignment of hits: central two 125.6 ns long time intervals correspond to hits in the signal windows, while the left and right intervals correspond to off-time background hits.

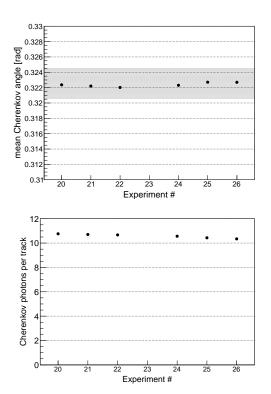


Figure 28: Detector performance as a function of time: Cherenkov angle (top) and number of photons (bottom) for ultra-relativistic muon tracks ($p > 4~{\rm GeV/}c$); the gray region indicates the $\pm 1\sigma_{\rm track}$ band for $4~{\rm GeV/}c$ pions.

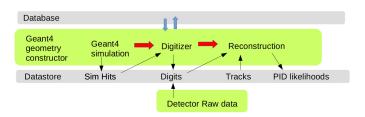


Figure 29: ARICH software scheme.

10.1. Geant4 simulation

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The geometry of the ARICH detector is implemented in detail in the Geant4 framework. This includes all the main components relevant to the emission, propagation, and detection of Cherenkov photons, as well as the detector support structures, cooling system, and neutron shielding and cabling material. Since the detector geometry is described elsewhere we only address here items particular to the simulation, which are also relevant when comparing the measured and simulated data.

Aerogel plane. In the simulation, all aerogel tiles of one layer, 523 have equal optical properties and thickness. The refractive in-524 dices of 1.045 and 1.055, and transmission lengths of 45 mm_{525} and 35 mm, are used for all the tiles in the up-stream and downstream layers respectively (the values given are at 400 nm, but 527 their full wavelength dependency as measured in the QA tests 528 is implemented in the simulation). Tiles are of four different 529 "wedge" shapes (different in each concentric ring of tiles) and 5590 have a uniform thickness of 20 mm. Tiles are placed at the center of tile slots which are formed by aluminum strips with,531 1 mm of thickness, with an additional 1 mm of gap between 532 the tile edge and aluminum, on all four sides of a tile (in total, 523 there is therefore a 3 mm of gap between the edges of aerogel₅₃₄ tiles). The black paper that covers the tile slots is, for the sake 535 of simplicity, not included in the simulation, but its effect of $_{536}$ photon absorption is mimicked by non-specified optical properties of the aluminum, which results in optical photons being⁵³⁷ killed upon hitting it.

Photon detector - HAPD. In the simulation, we construct the 540 photon detector module as a ceramic box, featuring the quartz⁵⁴¹ window on top, a vacuum inside, and a silicon APD sensor at 542 the bottom. The dependency of the quartz refractive index on 543 the wavelength is implemented by using data found in the lit-544 erature. The emission of photoelectrons from the photocathode and their propagation to the APDs is not included in the simulation. Instead, for the optical photons that hit the bottom surface of the quartz window, onto which the photocathode is coated, 548 the quantum efficiency curve is applied (we randomly select a number from 0 to 1 and compare it with Q.E. at the given photon wavelength). If the photon is registered as detected, it is550 killed and its position is passed to the so-called digitizer for the551 next steps of processing (as described in the following subsec-552 tion). On the other hand, if the photon is not detected, it is left to propagate further, either by being internally reflected in the quartz window or by entering into the HAPD where it can be then reflected from the APD back to the photocathode or absorbed. The reflectivity of the APD surface in the simulation is wavelength-independent and is tuned so that the fraction of ⁵⁵⁷ reflected photons agrees with the one observed in the measured 558 data. At this point, the same O.E. curve is used for all HAPDs,559 which is corrected to the exact values during the digitisation₅₆₀ step (see below).

Other components. Here we provide a few relevant comments on other detector components. The mirrors are implemented as

quartz planes coated with a reflective metal, where the reflectivity and its wavelength dependency are set to the values as obtained in QA measurements. The front-end electronics (HAPD front-end boards and merger boards) are implemented as simple boxes, of correct dimensions, made of material commonly used for effective PCB description. The geometry of cooling bodies (behind each FEB and merger board) and cooling pipes is implemented in fine details. On the other hand, the detector cabling (HV, LV, read out) is included by placing a simple homogeneous thin plane with the amount and type of material that effectively describes the cabling material, behind the photon-detector plane. Finally, the borated polyethylene neutron shield volumes are also included, with precisely described shapes and sizes

Since the peak Q.E. of HAPDs is $\sim 40\%$, only this fraction of emitted optical photons is actually propagated in the simulation, while the rest are killed immediately at the emission time. This allows to speed up the detector simulation without affecting its output.

10.2. Digitization

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In the digitizer module the photon hits obtained from the Geant4-based simulation are converted into a data format equivalent to that of the measured data (i.e., a collection of channel numbers for hit APD pixels). There are four processes that are performed at this stage:

- Pixelization: based on the registered photon hit position we calculate the pixel number to which this position corresponds. Here we assume that the emitted photoelectron only moves in the z-direction, i.e. along the magnetic field lines.
- Channel-by-channel Q.E. correction: at the simulation level a common wavelength dependence of Q.E. is used for all HAPDs. However, since relatively large differences in the Q.E. are observed between individual samples, and the Q.E. non-uniformity over the surface of individual sensors cannot be neglected, we apply a channel-by-channel Q.E. correction, using the measured Q.E. surface maps of individual HAPDs.
- Dead channel masking: about 5% of channels are nonoperational; we maintain a list of these channels in the database and use it for the production of simulated data.
- Effect of negative polarity cross-talk: if a single pixel is hit by a large number of photoelectrons, the efficiency of neighbouring pixels to detect photoelectron is reduced. This effect is included in the digitizer where we count the number of photoelectrons on each pixel and proportionally to it lower the efficiency of the neighbouring pixels.

The list of so-called digits, which contain the photon-detector module ID number, channel ID number, and a hit bitmap⁵ is the final output of the Geant4 simulation.

⁵These are four time-consecutive bits, which indicate whether the signal exceeded the threshold value in a given time bin or not.

The simulation of ARICH detector response is checked by $_{584}$ high momentum muon tracks from the $e^+e^- \rightarrow \mu^+\mu^-$ events, $_{585}$ comparing the Cherenkov ring image in measured and simu- $_{586}$ lated events. The top two plots of Fig. 30 show the recon- $_{587}$

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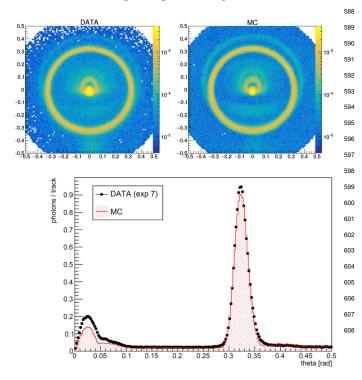


Figure 30: Calibration of the simulated detector response; top: comparison of accumulated Cherenkov ring images as observed in the measured data and the detector simulation; bottom: comparison of measured and simulated Cherenkov angle distributions (integral of top two plots over the ring azimuthal angle).

structed Cherenkov ring image in the angular coordinate system₆₁₁ of a track⁶ for the measured and simulated data. The image is₆₁₂ obtained as a normalized sum of Cherenkov rings from $O(10k)_{613}$ muon tracks. Several detailed features, such as Cherenkov pho-614 tons produced in the quartz window of photon detectors and 615 an "echo ring" originating from the non- converted photons re-616 flected from the APD surface back to the photocathode, can be₆₁₇ seen to be well reproduced in the simulation. Some discrepan-618 cies between the measured and simulated data can be seen in the peak produced by charged tracks in the window of photon₆₁₉ detectors at small Cherenkov angles. This arises due to the difficulty of correctly modeling the optical properties of the photocathode and the response of the avalanche photodiode to a large number of photons. Based on these observations mentioned effects will be adjusted for in the detector simulation. 624

10.3. Event reconstruction

Reconstructed tracks from the Belle II tracking system are extrapolated to the ARICH detector volume. For those that 628

pass through the aerogel layer, a likelihood function is constructed for each of the six different particle type hypotheses (e, μ, π, K, p, d) . The likelihood function compares the observed pattern of photon hits with the expected one for the given particle type hypothesis and track parameters (position, direction and momentum on the aerogel plane) as obtained from the track extrapolation.

The likelihood function is constructed as a product of probabilities of individual pixels recording the observed number of hits (which can only be 0 or 1 since we do not discriminate between single and multiple photon hits) for a given particle type hypothesis. The probability of pixel i being hit by m_i photoelectrons is given by the Poissonian distribution, i.e., $p_i = e^{-n_i} n_i^{m_i}/m_i!$, where n_i is the number of photoelectrons expected to hit the pixel i. The value of n_i is a sum of the expected number of hits from two radiator layers and from the background. The contribution of each radiator to the signal on the pixel i is calculated according to the probability distribution in the polar and azimuthal angles relative to the track direction over the solid angle subtended by the pixel. The method is discussed in detail in [37].

Following P. Baillon [38] and R. Forty [39] to construct the likelihood function, we first note that the probability of a pixel being fired or not is $1 - e^{-n_i}$ and e^{-n_i} , respectively, and the logarithm of the likelihood function is

$$\ln \mathcal{L} = \sum_{hit} \ln (1 - e^{-n_i}) + \sum_{no \ hit} \ln (e^{-n_i})$$
$$= \sum_{hit} [n_i + \ln (1 - e^{-n_i})] - \sum_{all} n_i = \sum_{hit} \ln (e^{n_i} - 1) - N,$$

where $hit / no \ hit / all$ indicates the subset of pixels included in the sum, and we note that the sum of n_i over all pixels is equal to the total number of photons expected to be detected (denoted by N). Instead of having to obtain n_i for all pixels, in this form evaluating the likelihood reduces to calculating n_i only for pixels that registered a hit, and to estimating N. Both n_i and N have to be evaluated for each particle type hypothesis. Finally, the difference of likelihoods of two hypotheses (e.g. $\ln \mathcal{L}^{\pi} - \ln \mathcal{L}^{K}$) is used for separation between particle species (π, K) .

10.4. Calibration and alignment

Calibrating the detector is essential due to its significant impact on algorithm performance. Calibration affects the expected number of photons per pixel (n_i) in the likelihood function, incorporating both background and signal contributions. The signal component relies on the detection efficiency of the pad (η_i) and the probability density function, which is determined by the Cherenkov angle resolution (σ_{θ}) . Without proper calibration, identification efficiencies decrease and misidentification probabilities increase.

The detector response and alignment with the tracking system were calibrated using recorded data, primarily from $e^+e^- \rightarrow \mu^+\mu^-$ events [37, 40]. This calibration process involved several steps. First, the operational parameters of the detector

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⁶In this system the track direction corresponds to (0,0) and the distance from ⁶³¹ the origin shows the photon direction polar angle, i.e. Cherenkov angle.

components were measured. Next, the detector was calibrated₆₈₇ using the acquired data. Finally, the crucial step for subsequent₆₈₈ physics analyses was determining the efficiencies and misiden₋₆₈₉ tification probabilities from beam collision data.

The reconstruction algorithms could access all the measured and calculated parameters in a central experiment database.

Cherenkov angle distribution for saturated rings is used to 6930 calculate the number of detected photons per track. With the 6944 procedure described above, the detection efficiency of each hit, 6954 η_i , and the total number of photons per hypothesis, N, can then 6956 be calculated.

To complete the calibration, the Cherenkov angle resolution, 698 σ_{θ} , must be optimized by aligning the detector [40]. From dis-699 placements at different positions of the detector, new alignment 700 constants are determined, leading to the correct σ_{θ} , which can 701 then be used in the algorithm.

11. Particle identification performance

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The ARICH detector has been running stably throughout all $_{707}$ running periods of the Belle II experiment. The fraction of dead $_{708}$ or noisy channels has been at the 5% level; as determined from $_{709}$ simulation, such a level of missing channels is by a large mar- $_{710}$ gin below the level that would impact the particle identification $_{711}$ performance of the device.

The performance of the detector was first checked by a large number of available muon tracks originating from the $e^+e^- \rightarrow_{712} \mu^+\mu^-$ events. Muons from these events have the energy of about 7 GeV, producing essentially saturated Cherenkov rings in the ARICH. From the bottom plot of Fig. 30 we determine ther13 number of signal Cherenkov photons and the Cherenkov an-714 gle resolution for measured data and simulation by fitting the715 obtained distributions with a single Gaussian function for the716 peak and a first-order polynomial for the background distribu-717 tion. The obtained numbers of signal photons per muon track718 are $N_{sig}^{data} = 11.38$ and $N_{sig}^{MC} = 11.27$ for the measured and simu-719 lated data respectively, while the corresponding Cherenkov an-720 gle resolutions (i.e. signal peak width) are $\sigma_c^{data} = 12.70$ mrad721 and $\sigma_c^{MC} = 12.75$ mrad (with negligible uncertainties from the722 fit).

We estimate the detector ability to discriminate between pions and kaons using pion and kaon tracks from $D^{*+} \rightarrow D^0[\rightarrow_{_{723}}$ $K^-\pi^+$] π^+_{slow} and D^{*-} \to \bar{D}^0 [\to $K^+\pi^-$] π^-_{slow} decay chains. Here, pion and kaon tracks can be identified independently of ARICH information, based on their charge in association with724 the charge of low-momentum pion $(\pi_{\mathrm{slow}}^{\pm})$ from $D^{*\pm}$. In addi-725 tion, the background level in this decay mode can be effectively⁷²⁶ reduced by requiring the difference of reconstructed invariant⁷²⁷ masses of D^* and D^0 mesons to be within a narrow window⁷²⁸ around the expected value ($|M_{D^*}-M_{D^0}-145.43~{
m MeV}/c^2|$ <729 1.5 MeV/ c^2 is used). We determine the efficiency of kaon iden-730 tification and pion misidentification probability from the signal₇₃₁ vield of reconstructed D^0 mesons, where pion or kaon track₇₃₂ used in the reconstruction is required to satisfy the imposed se-733 lection criteria on PID likelihood ratio $R[K/\pi]$ obtained from 734 the ARICH detector, with $R[K/\pi] = \mathcal{L}_K/(\mathcal{L}_K + \mathcal{L}_\pi)$. The D^{0}_{735}

signal yield is determined from the fit of D^0 invariant mass distribution using a Gaussian function for the signal and a constant value for the background distributions. An example of such a fit is shown in the top two plots of figure 31. Left (right) plot shows data distribution and fit of D^0 invariant mass for candidates with pion (kaon) track entering ARICH. Fainted points and lines show the case when no selection is imposed on $R[K/\pi]$ and solid points and lines after imposing a $R[K/\pi]$ requirement. Repeating such fit using different $R[K/\pi]$ criteria results in the bottom left plot of Fig. 31, which shows the obtained kaon identification efficiency at different pion misidentification probabilities. The right bottom plot shows the dependence of these two quantities on the track momentum, where a fixed criterium of $R[K/\pi] > 0.5$ is used at all points. The obtained performance is slightly lower than expected from the simulations (up to a few % in K identification efficiency), further improvements are under study. In a similar manner, $\Lambda \to p\pi^-$ decays are utilized to verify the pion-proton separation; at 4 GeV/c, the proton identification efficiency is 91% with a pion misidentification probability of 8%. We note that the hadron identification performance of all involved subsystems in the Belle II spectrometer is discussed in detail in a dedicated report [41]. To summarize, the ARICH detector provides excellent pion-kaon, pion-proton and kaon-proton discrimination, and at momenta below 1 GeV/c a modest discrimination between pions, muons and electrons.

12. Summary

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The Aerogel RICH detector in the forward end-cap of the Belle II spectrometer is an integral part of the Belle II particle identification system. It is based on a novel multi-layer radiator configuration and utilizes a new type of single-photon sensor, hybrid avalanche photodetectors (HAPD). It provides excellent discrimination between pions and kaons in the full kinematic range of the experiment (up to 4 GeV/c). The detector has been performing very well throughout the Belle II data-taking and is expected to continue contributing to the future physics harvest of the experiment.

13. Acknowledgements

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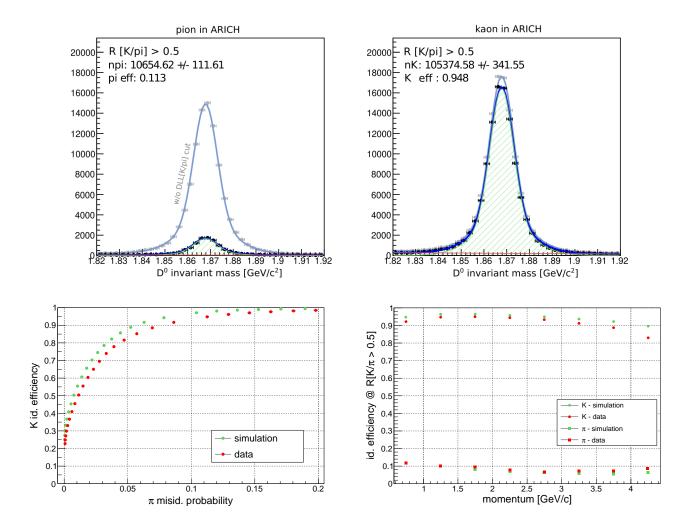


Figure 31: ARICH detector, performance. Top: examples of fits of the $K^{\mp}\pi^{\pm}$ invariant mass distributions from which we determine kaon identification efficiency and pion misidentification probability at a given criterion on $R[K/\pi]$. Bottom left: kaon identification efficiency versus pion misidentification probability for all kaon/pion tracks from D^0 decays that enter the ARICH detector; right: kaon identification efficiency and pion misidentification probability as a function of track momentum for a fixed likelihood ratio, $R[K/\pi] > 0.5$.

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